# +3.3V Low Power, $\pm 15 k$ V ESD-Protected, Fail-Safe, RS-422 Transceivers 

## UM3488EESA SOP8 UM3488EEPA DIP8 UM3491EESE SOP14 <br> UM3491EEPE DIP14

## General Description

The UM3488/UM3491 is $\pm 15 \mathrm{kV}$ electrostatic discharge (ESD)-protected, high-speed transceivers for RS-422 communication that contain one driver and one receiver. The UM3491 contains an additional receiver and driver enable control. The device features fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be a logic high if all transmitters on a terminated bus are disabled (high impedance). The UM3488/UM3491 allows transmit speeds up to 10 Mbps . The device features enhanced ESD protection. All transmitter outputs and receiver inputs are protected to $\pm 15 \mathrm{kV}$ using the Human Body Model.
These transceivers typically draw $180 \mu \mathrm{~A}$ of supply current when unloaded, or when fully loaded with the drivers disabled.
The device has a $1 / 8$-unit-load receiver input impedance that allows up to 256 transceivers on the bus. The UM3488/UM3491 is intended for full-duplex communications.

## Applications

- RS-422 Communications
- Level Translators
- Transceivers for EMI-Sensitive Applications
- Industrial-Control Local Area Networks


## Features

- ESD Protection for RS-422 I/O Pins $\pm 15 \mathrm{kV}$, Human Body Model
- True Fail-Safe Receiver while Maintaining EIA/TIA-422 Compatibility
- Maximum Data Rate up to 10 Mbps
- Error-Free Data Transmission
- 1nA Low-Current Shutdown Mode (UM3491)
- Allow up to 256 Transceivers on the Bus


## Selector Guide

| Part <br> Number | Half/Full <br> Duplex | Data <br> Rate <br> (Mbps) | Slew- <br> Rate <br> Limited | Low- <br> Power <br> Shutdown | Receiver/ <br> Driver <br> Enable | Quiescent <br> Current <br> $(\boldsymbol{\mu A )}$ | Transceivers <br> On <br> Bus | Pin <br> Count |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| UM3488 | full | 10 | Yes | No | No | 180 | 256 | 8 |
| UM3491 | full | 10 | Yes | Yes | Yes | 180 | 256 | 14 |

Ordering Information

| Part Number | Temperature Range | Packaging Type | Shipping Qty |
| :---: | :---: | :---: | :---: |
| UM3488EESA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | SOP8 | 2500pcs/13 Inch Tape \& Reel |
| UM3488EEPA | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | DIP8 | 50pcs/Tube |
| UM3491EESE | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | SOP14 | 2500pcs/13 Inch Tape \& Reel |
| UM3491EEPE | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | DIP14 | 25pcs/Tube |

Pin Configurations

|  |  |  |
| :---: | :---: | :---: |
|  |  |  |

## Absolute Maximum Ratings

| Symbol | Parameter | Value | Unit |
| :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {CC }}$ | Supply Voltage | +7 | V |
|  | Control Input Voltage ( $\overline{\mathrm{RE}}, \mathrm{DE}$ ) | -0.3 V to $(\mathrm{VCC}+0.3 \mathrm{~V})$ | V |
|  | Driver Input Voltage (DI) | -0.3 V to ( $\mathrm{VCC}+0.3 \mathrm{~V}$ ) | V |
|  | Driver Output Voltage (A, B, Y, Z) | $\pm 13$ | V |
|  | Receiver Input Voltage (A, B) | $\pm 25$ | V |
|  | Receiver Output Voltage (RO) | -0.3 V to ( $\mathrm{VCC}+0.3 \mathrm{~V}$ ) | V |
| $\mathrm{P}_{\mathrm{D}}$ | 8-Pin SO (derate $9.09 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) | 520 | mW |
|  | 8 -Pin Plastic DIP (derate $9.09 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) | 727 |  |
|  | 14-Pin Plastic DIP (derate $10.0 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) | 800 |  |
|  | 14-Pin SO (derate $8.33 \mathrm{~mW} /{ }^{\circ} \mathrm{C}$ above $+70^{\circ} \mathrm{C}$ ) | 667 |  |
| $\mathrm{T}_{\text {A }}$ | Ambient Temperature | -40 to +85 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {STG }}$ | Storage Temperature Range | -65 to +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{L}}$ | Lead Temperature for Soldering 10 seconds | +300 | ${ }^{\circ} \mathrm{C}$ |

## DC Electrical Characteristics

$\left(\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}\right.$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.) (Note 1)

| Parameter | Symbol | Test Conditions |  | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |  |  |
| Differential Driver Output (No Load) | $\mathrm{V}_{\text {OD1 }}$ | Figure 3 |  |  |  | $\mathrm{V}_{\mathrm{CC}}$ | V |
| Differential Driver Output | $\mathrm{V}_{\mathrm{OD} 2}$ | Figure 3, R $=50 \Omega$ |  | 1.8 |  | $\mathrm{V}_{\mathrm{CC}}$ | V |
| Differential Driver Output | $\mathrm{V}_{\text {OD3 }}$ | Figure 3, R = $27 \Omega$ |  | 1.3 |  | $\mathrm{V}_{\mathrm{CC}}$ | V |
| Change-in-Magnitude of Differential Output Voltage (Note 2) | $\Delta \mathrm{V}_{\mathrm{OD}}$ | Figure 3, R $=50 \Omega$ |  |  |  | 0.2 | V |
| Driver Common-Mode Output Voltage | $\mathrm{V}_{\text {OC }}$ | Figure 3, R $=50 \Omega$ |  |  |  | 3.0 | V |
| Input High Voltage | $\mathrm{V}_{\mathrm{IH}}$ | DE, DI, $\overline{\mathrm{RE}}$ |  | 2.0 |  |  | V |
| Input Low Voltage | $\mathrm{V}_{\text {IL }}$ | DE, DI, $\overline{\mathrm{RE}}$ |  |  |  | 0.8 | V |
| DI Input Hysteresis | $\mathrm{V}_{\mathrm{HYS}}$ |  |  |  | 100 |  | mV |
| Driver Short-Circuit Output Current (Note 3) | $\mathrm{V}_{\text {OD1 }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {OUT }} \leq \mathrm{V}_{\text {CC }}$ |  | -250 |  |  |  |
|  |  | $0 \mathrm{~V} \leq \mathrm{V}_{\text {OUT }} \leq 12 \mathrm{~V}$ |  |  |  | 250 |  |
| RECEIVER |  |  |  |  |  |  |  |
| Input Current (A and B) | $\mathrm{I}_{\text {IN }}$ | $\begin{gathered} \mathrm{DE}=\mathrm{GND}, \\ \mathrm{~V}_{\mathrm{CC}}=\mathrm{GND} \text { or } \\ 3.465 \mathrm{~V} \end{gathered}$ | $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}$ |  |  | 125 | $\mu \mathrm{A}$ |
|  |  |  | $\mathrm{V}_{\text {IN }}=-7 \mathrm{~V}$ |  |  | -75 |  |
| Receiver Differential Threshold Voltage | $\mathrm{V}_{\text {TH }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{Cm}} \leq 12 \mathrm{~V}$ |  | -200 | -125 | -50 | mV |
| Receiver Input Hysteresis | $\Delta \mathrm{V}_{\text {TH }}$ |  |  |  | 25 |  | mV |
| Receiver Output High Voltage | $\mathrm{V}_{\mathrm{OH}}$ | $\mathrm{I}_{\mathrm{O}}=-4 \mathrm{~mA}, \mathrm{~V}_{\text {ID }}=-50 \mathrm{mV}$ |  | $\begin{gathered} \hline \mathrm{V}_{\mathrm{CC}} \\ -0.4 \end{gathered}$ |  |  | V |
| Receiver Output Low Voltage | $\mathrm{V}_{\text {OL }}$ | $\mathrm{I}_{\mathrm{O}}=4 \mathrm{~mA}, \mathrm{~V}_{\text {ID }}=-200 \mathrm{mV}$ |  |  |  | 0.4 | V |
| Three-State Output Current at Receiver | $\mathrm{I}_{\text {OzR }}$ | $0.4 \mathrm{~V} \leq \mathrm{V}_{\mathrm{O}} \leq 2.4 \mathrm{~V}$ |  |  |  | $\pm 1$ | $\mu \mathrm{A}$ |
| Receiver Input Resistance | $\mathrm{R}_{\text {IN }}$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\mathrm{CM}} \leq 12 \mathrm{~V}$ |  | 96 |  |  | $\mathrm{k} \Omega$ |
| Receiver Output Short Circuit Current | $\mathrm{I}_{\text {OSR }}$ | $0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{RO}} \leq \mathrm{V}_{\mathrm{CC}}$ |  | $\pm 7$ |  | $\pm 95$ | mA |
| SUPPLY CURRENT |  |  |  |  |  |  |  |
| Supply Current | $\mathrm{I}_{\text {CC }}$ | $\begin{gathered} \text { No load, } \\ \mathrm{DE} \\ =\mathrm{DI}=\mathrm{GND} \\ \text { or } \mathrm{V}_{\mathrm{CC}} \end{gathered}$ | $\overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{CC}}$ |  | 20 | 60 | $\mu \mathrm{A}$ |
|  |  |  | $\overline{\mathrm{RE}}=\mathrm{GND}$ |  | 180 | 300 |  |


| Supply Current in Shutdown <br> Mode | $\mathrm{I}_{\mathrm{SHDN}}$ | $\mathrm{DE}=\mathrm{GND}, \mathrm{V}_{\mathrm{RE}}=\mathrm{V}_{\mathrm{CC}}$ |  | 0.001 | 10 | $\mu \mathrm{~A}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ESD Protection for Y, Z, A, B |  | Human Body Model |  | $\pm 15$ |  | kV |

Note 1: All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.
Note 2: $\Delta \mathrm{V}_{\mathrm{OD}}$ and $\Delta \mathrm{V}_{\mathrm{OC}}$ are the changes in $\mathrm{V}_{\mathrm{OD}}$ and $\mathrm{V}_{\mathrm{OC}}$, respectively, when the DI input changes state.
Note 3: Maximum current level applies to peak current just prior to foldback-current limiting; minimum current level applies during current limiting.

## Switching Characteristics

$\left(\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V} \pm 5 \%, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}\right.$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted. Typical values are at $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$.)

| Parameter | Symbol | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Driver Input-to-Output | $\mathrm{t}_{\text {DPLH }}$ | Figures 5 and $7, \mathrm{R}_{\text {DIFF }}=54 \Omega$,$\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ | 10 | 30 | 60 | ns |
|  | $\mathrm{t}_{\text {DPHL }}$ |  | 10 | 30 | 60 |  |
| Driver Output Skew <br> $\left\|\mathrm{t}_{\text {DPLH }}-\mathrm{t}_{\text {DPH }} \mathrm{L}\right\|$ | $\mathrm{t}_{\text {DSKEW }}$ | Figures 5 and $7, \mathrm{R}_{\text {DIFF }}=54 \Omega$, $\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ |  | 10 | 25 | ns |
| Driver Rise or Fall Time | $\mathrm{t}_{\mathrm{DR}}, \mathrm{t}_{\mathrm{DF}}$ | Figures 5 and $7, \mathrm{R}_{\text {DIFF }}=54 \Omega$, $\mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$ | 5 | 15 | 30 | ns |
| Maximum Data Rate | $\mathrm{f}_{\text {MAX }}$ |  |  |  | 10 | Mbps |
| Driver Enable to Output High | $\mathrm{t}_{\text {DZH }}$ | Figures 6 and 8, $\mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, <br> S2 closed |  | 40 | 70 | ns |
| Driver Enable to Output Low | $\mathrm{t}_{\text {DZL }}$ | Figures 6 and 8, $\mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, <br> S1 closed |  | 40 | 70 | ns |
| Driver Disable Time from Low | $\mathrm{t}_{\text {DLZ }}$ | Figures 6 and $8, C_{L}=15 \mathrm{pF}$, S1 closed |  | 40 | 70 | ns |
| Driver Disable Time from High | $\mathrm{t}_{\text {DHZ }}$ | Figures 6 and $8, C_{L}=15 \mathrm{pF}$, S2 closed |  | 40 | 70 | ns |
| Receiver Input to Output | $\begin{aligned} & \mathrm{t}_{\text {RPLH }}, \\ & \mathrm{t}_{\text {RPHL }} \end{aligned}$ | Figures 9 and $11 ;\left\|\mathrm{V}_{\mathrm{ID}}\right\| \geq 2.0 \mathrm{~V}$; rise and fall time of $\mathrm{V}_{\mathrm{ID}} \leq 15 \mathrm{~ns}$ | 20 | 100 | 180 | ns |
| $\left\|\mathrm{t}_{\text {RPLH }}-\mathrm{t}_{\text {RPHL }}\right\|$ Differential Receiver Skew | $\mathrm{t}_{\text {RSKD }}$ | Figures 9 and $11 ;\left\|\mathrm{V}_{\mathrm{ID}}\right\| \geq 2.0 \mathrm{~V}$; rise and fall time of $\mathrm{V}_{\mathrm{ID}} \leq 15 \mathrm{~ns}$ |  | 13 |  | ns |
| Receiver Enable to Output Low | $\mathrm{t}_{\text {RZL }}$ | Figures 4 and $10, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, <br> S1 closed |  | 40 | 100 | ns |
| Receiver Enable to Output High | $\mathrm{t}_{\text {RZH }}$ | Figures 4 and $10, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, S2 closed |  | 40 | 100 | ns |
| Receiver Disable Time from Low | $\mathrm{t}_{\text {RLZ }}$ | Figures 4 and $10, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, <br> S1 closed |  | 40 | 100 | ns |
| Receiver Disable Time from High | $\mathrm{t}_{\text {RHZ }}$ | Figures 4 and $10, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, S2 closed |  | 40 | 100 | ns |
| Time to Shutdown | $\mathrm{t}_{\text {SHDN }}$ | (Note 4) | 50 | 200 | 600 | ns |
| Driver Enable from Shutdown to Output High | $\mathrm{t}_{\mathrm{DZH}(\mathrm{SHDN})}$ | Figures 6 and $8, C_{L}=15 \mathrm{pF}$, S2 closed |  | 40 | 200 | ns |
| Driver Enable from Shutdown to Output Low | $\mathrm{t}_{\text {DZL } \text { (SHDN) }}$ | Figures 6 and $8, C_{L}=15 \mathrm{pF}$, <br> S1 closed |  | 40 | 200 | ns |
| Receiver Enable from Shutdown- to-Output High | $\mathrm{t}_{\text {RZH (SHDN })}$ | Figures 4 and $10, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, <br> S2 closed |  | 150 | 500 | ns |
| Receiver Enable from Shutdown- to-Output Low | $\mathrm{t}_{\text {RZL }}$ (SHDN) | Figures 4 and $10, \mathrm{C}_{\mathrm{L}}=100 \mathrm{pF}$, S1 closed |  | 150 | 500 | ns |

Note 4: The device is put into shutdown by bringing $\overline{\mathrm{RE}}$ high and DE low. If the enable inputs are in this state for less than 50 ns , the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600 ns , the device is guaranteed to have entered shutdown.

UM3488/UM3491
Typical Operating Characteristics
$\left(\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}\right.$, unless otherwise noted. $)$

No Load Supply Current vs.
Temperature


Output Current vs. Receiver Output Low Voltage


Output Current vs.Receiver Output
High Voltage


Receiver Output High Voltage vs. Temperature


UM3488/UM3491

Typical Operating Characteristics (Continued)
( $\mathrm{V}_{\mathrm{CC}}=+3.3 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$, unless otherwise noted.)


Driver Differential Output Voltage vs. Temperature


Driver Output Current vs.Differential Output Voltage


UM3488/UM3491

Pin Description

| Pin Number |  | Symbol | Function |
| :---: | :---: | :---: | :--- |
| UM3488 | UM3491 |  |  |
| - | 1 | NC | Not Connected |
| 2 | 2 | RO | Receiver Output. When $\overline{\mathrm{RE}}$ is low and if A - B $\geq-50 \mathrm{mV}$, RO <br> will be high; if A $-\mathrm{B} \leq-200 \mathrm{mV}, \mathrm{RO}$ will be low. |
| - | 3 | $\overline{\mathrm{RE}}$ | Receiver Output Enable. Drive $\overline{\mathrm{RE}}$ low to enable RO; RO is <br> high impedance when $\overline{\mathrm{RE}}$ is high. Drive $\overline{\mathrm{RE}}$ high and DE <br> low to enter low-power shutdown mode. |
| - | 4 | DE | Driver Output Enable. Drive DE high to enable driver outputs. <br> These outputs are high impedance when DE is low. Drive RE <br> high and DE low to enter low-power shutdown mode. |
| 3 | 5 | DI | Driver Input. With DE high, a low on DI forces non-inverting <br> output low and inverting output high. Similarly, a high on DI <br> forces non-inverting output high and inverting output low. |
| 4 | 6 | GND | Ground |
| 4 | 7 | GND | Ground |
| - | 8 | NC | Not Connected |
| 5 | 9 | Y | Non-inverting Driver Output |
| 6 | 10 | Z | Inverting Driver Output |
| 7 | 11 | B | Inverting Receiver Input |
| 8 | 12 | A | Non-inverting Receiver Input |
| - | 13 | NC | Not Connected |
| 1 | 14 | VCC | Positive Supply 3.135V $\leq$ VCC $\leq 3.465 \mathrm{~V}$ |

## Functions Tables

| IRANSMITTING |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | OUTPUTS |  |
| $\overline{\mathrm{RE}}$ | DE | DI | Z | Y |
| X | 1 | 1 | 0 | 1 |
| X | 1 | 0 | 1 | 0 |
| 0 | 0 | X | High-Z | High-Z |
| 1 | 0 | X | Shutdown |  |


| RECEIVING |  |  |  |
| :---: | :---: | :---: | :---: |
| INPUTS |  |  | OUTPUT |
| $\overline{\mathrm{RE}}$ | DE | $\mathrm{A}-\mathrm{B}$ | RO |
| 0 | X | $\geq-0.05 \mathrm{~V}$ | 1 |
| 0 | X | $\leq-0.2 \mathrm{~V}$ | 0 |
| 0 | X | Open/Short | 1 |
| 1 | 1 | X | High-Z |
| 1 | 0 | X | Shutdown |

## Typical Operating Circuit



Figure 1: UM3491 pin configuration and typical full-duplex operating circuit


Figure 2: Typical Full-Duplex RS-422 Network

## Detailed Description

The UM3488/UM3491 high-speed transceivers for RS-422 communication contain one driver and one receiver. The device features fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted, or when they are connected to a terminated transmission line with all drivers disabled.
The UM3488/UM3491 offer higher driver output slew-rate limits, allowing transmit speeds up to 10Mbps.
The UM3488/UM3491 is full-duplex transceiver. It operates from a single +3.3 V supply. Drivers are output short-circuit current limited. Thermal shutdown circuitry protects drivers against excessive power dissipation. When activated, the thermal shutdown circuitry places the driver outputs into a high- impedance state.

## Receiver Input Filtering

The receivers of the UM3488/UM3491 incorporate input filtering in addition to input hysteresis. This filtering enhances noise immunity with differential signals that have very slow rise and fall times. Receiver propagation delay increases by $20 \%$ due to this filtering.

## Fail-Safe

The UM3488/UM3491 guarantees a logic-high receiver output when the receiver inputs are shorted or open, or when they are connected to a terminated transmission line with all drivers disabled. This is done by setting the receiver threshold between -50 mV and -200 mV . If the differential receiver input voltage (A-B) is greater than or equal to -50 mV , RO is logic high. If A-B is less than or equal to -200 mV , RO is logic low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to 0 V by the termination. With the receiver thresholds of the UM3488/UM3491, this results in a logic high with a 50 mV minimum noise margin. Unlike previous fail-safe devices, the -50 mV to -200 mV threshold complies with the $\pm 200 \mathrm{mV}$ EIA/TIA-422 standard.

## $\pm 15 \mathrm{kV}$ ESD Protection

As with all Union devices, ESD-protection structures are incorporated on all pins to protect against electrostatic discharges encountered during handling and assembly. The driver outputs and receiver inputs of the UM3488/UM3491 have extra protection against static electricity. Union's engineers have developed state-of-the-art structures to protect these pins against ESD of $\pm 15 \mathrm{kV}$ without damage.
The ESD-protected pins are tested with reference to the ground pin in a powered-down condition. They are tested to $\pm 15 \mathrm{kV}$ using the Human Body Model.

## Test Circuit



Figure 3. Driver DC Test Load


Figure 5. Driver Timing Test Circuit


Figure 7. Driver Propagation Delays


Figure 9. Receiver Propagation Delays


Figure 4. Receiver Enable/Disable Timing Test Load


Figure 6. Driver Enable and Disable Timing Test Load


Figure 8. Driver Enable and Disable Times


Figure 10. Receiver Enable and Disable Times


Figure 12: Line Repeater

## Applications Information

## 256 Transceivers on the Bus

The standard RS-422 receiver input impedance is $12 \mathrm{k} \Omega$ (one-unit load), and the standard driver can drive up to 32 unit loads. The UM3491 has a $1 / 8$-unit-load receiver input impedance ( $96 \mathrm{k} \Omega$ ), allowing up to 256 transceivers to be connected in parallel on one communication line. Any combination of these devices and/or other RS-422 transceivers with a total of 32 unit loads or less can be connected to the line.

## Reduced EMI and Reflections

The UM3488/UM3491 is slew-rate limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Its high-frequency harmonic components are much lower in amplitude, and the potential for EMI is significantly reduced.
In general, a transmitter's rise time relates directly to the length of an unterminated stub, which can be driven with only minor waveform reflections. The following equation expresses this relationship conservatively:

$$
\text { Length }=\mathrm{t}_{\text {RISE }} /(10 \times 1.5 \mathrm{~ns} / \mathrm{ft})
$$

where $\mathrm{t}_{\text {RISE }}$ is the transmitter's rise time.

## Low-Power Shutdown Mode (UM3491)

Low-power shutdown mode is initiated by bringing both $\overline{\mathrm{RE}}$ high and DE low. In shutdown, the devices typically draw only 1 nA of supply current. $\overline{\mathrm{RE}}$ and DE may be driven simultaneously; the parts are guaranteed not to enter shutdown if $\overline{\mathrm{RE}}$ is high and DE is low for less than 50 ns . If the inputs are in this state for at least 600 ns , the parts are guaranteed to enter shutdown.
Enable times $\mathrm{t}_{\mathrm{zH}}$ and $\mathrm{t}_{\mathrm{zL}}$ in the Switching Characteristics tables assume the part was not in a low-power shutdown state. Enable times $\mathrm{t}_{\mathrm{ZH}(\mathrm{SHDN})}$ and $\mathrm{t}_{\mathrm{ZL}(\mathrm{SHDN})}$ assume the parts were shut down. It takes drivers and receivers longer to become enabled from low-power shutdown mode ( $\mathrm{t}_{\mathrm{ZH}(\mathrm{SHDN})}$, $\left.\mathrm{t}_{\mathrm{ZH}(\text { SHDN })}\right)$ than from driver/receiver-disable mode ( $\left.\mathrm{t}_{\mathrm{ZH}}, \mathrm{t}_{\mathrm{ZL}}\right)$.

## Driver Output Protection

Two mechanisms prevent excessive output current and power dissipation caused by faults or by bus contention. The first, a foldback current limit on the output stage, provides immediate protection against short circuits over the whole common-mode voltage range. The second, a thermal shutdown circuit, forces the driver outputs into a high-impedance state if the die temperature becomes excessive.

## Line Length vs. Data Rate

The RS-422 standard covers line lengths up to 4000 feet. For line lengths greater than 4000 feet, use the repeater application shown in Figure 12.

## Package Information

## UM3488EESA SOP8

Outline Drawing

| Top View <br> Side View | End View | DIMENSIONS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Symbol | MILLIMETERS |  | INCHES |  |
|  |  |  | Min | Max | Min | Max |
|  |  | A | 1.350 | 1.750 | 0.053 | 0.069 |
|  |  | A1 | 0.100 | 0.250 | 0.004 | 0.010 |
|  |  | A2 | 1.350 | 1.550 | 0.053 | 0.061 |
|  |  | b | 0.33 | 0.51 | 0.013 | 0.020 |
|  |  | c | 0.170 | 0.250 | 0.006 | 0.010 |
|  |  | D | 4.700 | 5.100 | 0.185 | 0.200 |
|  |  | E | 3.800 | 4.000 | 0.150 | 0.157 |
|  |  | E1 | 5.800 | 6.200 | 0.228 | 0.244 |
|  |  | e | 1.270 (BSC) |  | 0.050 (BSC) |  |
|  |  | L | 0.400 | 1.270 | 0.016 | 0.050 |
|  |  | $\theta$ | $0^{\circ}$ | $8^{\circ}$ | $0^{\circ}$ | $8^{\circ}$ |

## Land Pattern

|  | NOTES: <br> 1. Compound dimension: $4.90 \times 3.90$; <br> 2. Unit: mm; <br> 3. General tolerance $\pm 0.05 \mathrm{~mm}$ unless otherwise specified; <br> 4. The layout is just for reference. |
| :---: | :---: |

Tape and Reel Orientation


## UM3488EEPA DIP8

Outline Drawing


Tape and Reel Orientation


## UM3491EESE SOP14

Outline Drawing

|  |  | DIM | NSION |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | Symbol | MILLI | ETERS | INC | HES |
|  | Symbor | Min | Max | Min | Max |
|  | A | 1.350 | 1.750 | 0.053 | 0.069 |
| $\bigcirc$ | A1 | 0.100 | 0.250 | 0.004 | 0.010 |
|  | A2 | 1.250 | 1.650 | 0.050 | 0.066 |
| （1） | A3 | 0.550 | 0.750 | 0.022 | 0.030 |
|  | b | 0.360 | 0.490 | 0.014 | 0.020 |
| － | c | 0.170 | 0.250 | 0.006 | 0.010 |
|  | D | 8.530 | 8.730 | 0.341 | 0.349 |
| 田目目目目目 | E | 5.800 | 6.200 | 0.228 | 0.244 |
|  | E1 | 3.800 | 4.000 | 0.152 | 0.160 |
| ${ }_{03}+1 /$ | e | 1.27 | SC | 0.05 | BSC |
| $\vec{\theta}^{\left(\frac{3}{4}\right.}$ | L | 0.450 | 0.800 | 0.018 | 0.032 |
|  | L1 |  |  | 0.04 | REF |
| 寺04 | L2 | 0.25 |  | 0.01 | BSC |
|  | $\theta 1$ | $6^{\circ}$ | $10^{\circ}$ | $6^{\circ}$ | $10^{\circ}$ |
|  | $\theta 2$ | $6^{\circ}$ | $10^{\circ}$ | $6^{\circ}$ | $10^{\circ}$ |
|  | $\theta 3$ | $5^{\circ}$ | $9^{\circ}$ | $5^{\circ}$ | $9^{\circ}$ |
|  | $\theta 4$ | $5^{\circ}$ | $9^{\circ}$ | $5^{\circ}$ | $9^{\circ}$ |

## Land Pattern

|  | NOTES： <br> 1．Compound dimension： $8.63 \times 3.90$ ； <br> 2．Unit：mm； <br> 3．General tolerance $\pm 0.05 \mathrm{~mm}$ unless otherwise specified； <br> 4．The layout is just for reference． |
| :---: | :---: |

Tape and Reel Orientation


UM3488/UM3491

## UM3491EEPE DIP14

Outline Drawing

|  |  | DIMENSIONS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Symbol | MILLIMETERS |  | INCHES |  |
|  |  |  | Min | Max | Min | Max |
|  |  | A | - | 5.08 | - | 0.200 |
|  |  | A1 | 0.38 | - | 0.015 | - |
|  |  | A2 | 3.18 | 4.45 | 0.125 | 0.175 |
|  |  | A3 | 1.40 | 2.03 | 0.055 | 0.080 |
|  |  | b | 0.41 | 0.56 | 0.016 | 0.022 |
|  |  | b1 | 1.14 | 1.65 | 0.045 | 0.065 |
|  |  | C | 0.20 | 0.30 | 0.008 | 0.012 |
|  |  | D | 18.67 | 19.43 | 0.735 | 0.765 |
|  |  | D1 | 0.13 | 2.03 | 0.005 | 0.080 |
|  |  | E | 7.62 | 8.26 | 0.300 | 0.325 |
|  |  | E1 | 6.10 | 7.87 | 0.240 | 0.310 |
|  |  | e | 2.54 | - | 0.100 | - |
|  |  | eA | 7.62 | - | 0.300 | - |
|  |  | eB | - | 10.16 | - | 0.400 |
|  |  | L | 2.92 | 3.81 | 0.115 | 0.150 |

Tape and Reel Orientation


## IMPORTANT NOTICE

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Union Semiconductor, Inc
Add: Unit 606, No. 570 Shengxia Road, Shanghai 201210
Tel: 021-51093966
Fax: 021-51026018
Website: www.union-ic.com

