

Motor / Actuator / Drivers for DC Brush Motor Series

# Automotive 6ch Half Bridge Driver with SPI Control

## BD16936EFV-M

### General Description

The BD16936EFV-M is 6ch Half Bridge Driver for automotive applications. It can drive compact DC brush motors directly and each output can be controlled in three modes (High, Low and High Impedance). MCU can control the driver via 16bit Serial Interface (SPI). The part is 60V rated with Low ON Resistance packaged in compact HTSSOP-28 package, which contributes to realize high reliability, low energy consumption and low cost.

### Features

- AEC-Q100 Qualified(Note 1)
- 1.0A DMOS half Bridge 6 circuits
- Three modes Control (High Output, Low Output, Hi-Z)
- Low standby current
- Built-in Protection diode against output reverse voltage
- Over Current Detection(OCD)
- Over Voltage Protection at output power supply stage(OVP)
- Under Voltage Lock Out at output power supply stage(UVLO)
- Thermal Shut Down(TSD)  
(Note 1: Grade 2)

### Key Specifications

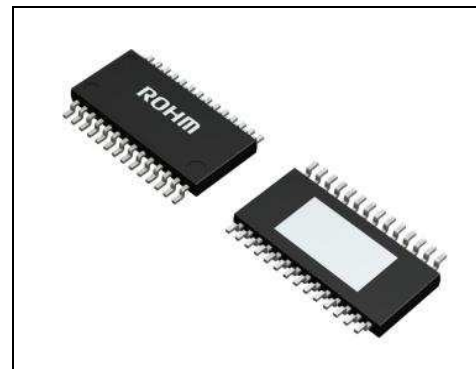
- Supply Voltage 8V to 36V
- Operating Temperature Range -40°C to +110°C
- Output Current 1.0A
- Output ON Resistance (High Side) 2.00Ω(Typ)
- Output ON Resistance (Low Side) 1.30Ω(Typ)

### Package

HTSSOP-B28

### W(Typ) x D(Typ) x H(Max)

9.70mm x 6.40mm x 1.00mm



HTSSOP-B28

### Applications(Note 2)

Automotive Body Electronics, HVAC, Door Mirrors, etc.

### Typical Application Circuit

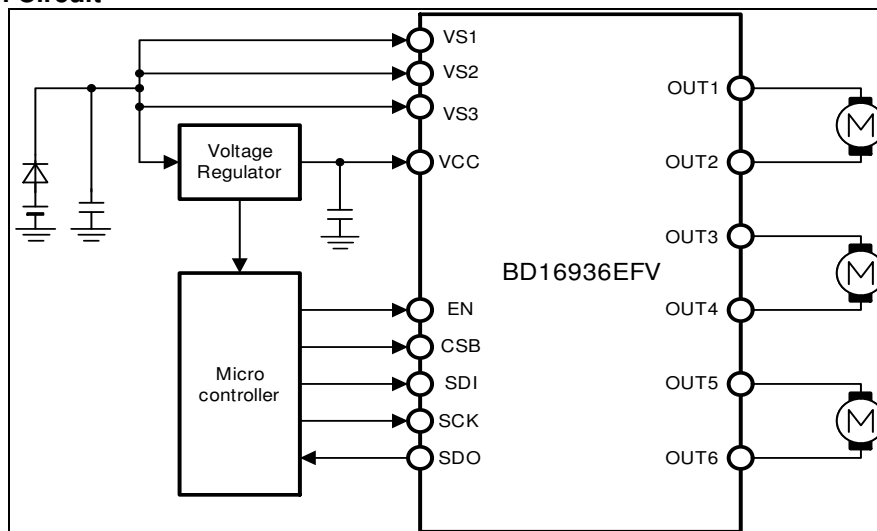


Figure 1. Typical Application Circuit

(Note 2) Please make sure you consult our company sales representative before mass production of this IC, if used other than Door Mirror and HVAC.

○Product structure : Silicon monolithic integrated circuit ○This product has no designed protection against radioactive rays

Pin Configuration

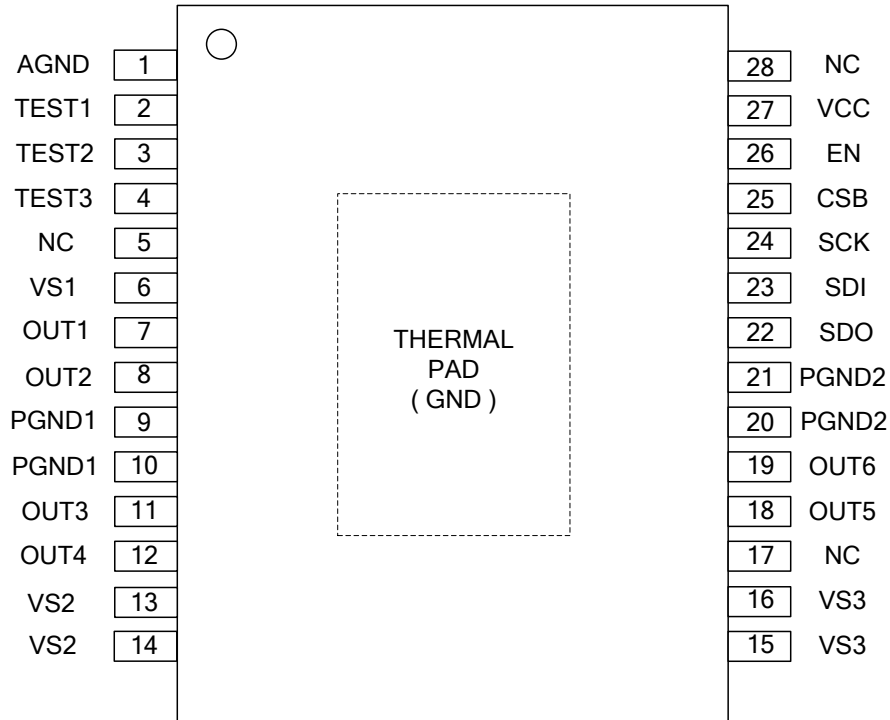


Figure 2. Pin Configuration (HTSSOP-B28)

Pin Description

PIN No.	Symbol	Function	PIN No.	Symbol	Function
1	AGND	Small signal GND <sup>(Note 1)</sup>	28	NC	-
2	TEST1	TEST1 input <sup>(Note 2)</sup>	27	VCC	Power supply
3	TEST2	TEST2 input <sup>(Note 2)</sup>	26	EN	Enable input
4	TEST3	TEST3 output <sup>(Note 3)</sup>	25	CSB	SPI chip select input
5	NC	-	24	SCK	SPI clock input
6	VS1	Power supply 1 at output stage	23	SDI	SPI data input
7	OUT1	Half bridge output 1	22	SDO	SPI data output
8	OUT2	Half bridge output 2	21	PGND2	Output GND2
9	PGND1	Output GND1	20	PGND2	Output GND2
10	PGND1	Output GND1	19	OUT6	Half bridge output 6
11	OUT3	Half bridge output 3	18	OUT5	Half bridge output 5
12	OUT4	Half bridge output 4	17	NC	-
13	VS2	Power supply 2 at output stage	16	VS3	Power supply 3 at output stage
14	VS2	Power supply 2 at output stage	15	VS3	Power supply 3 at output stage

(Note 1) Connect to ADGND for power dissipation.

(Note 2) Connect TEST1 and TEST2 to AGND

(Note 3) Keep TEST3 electrically open.

Block Diagram

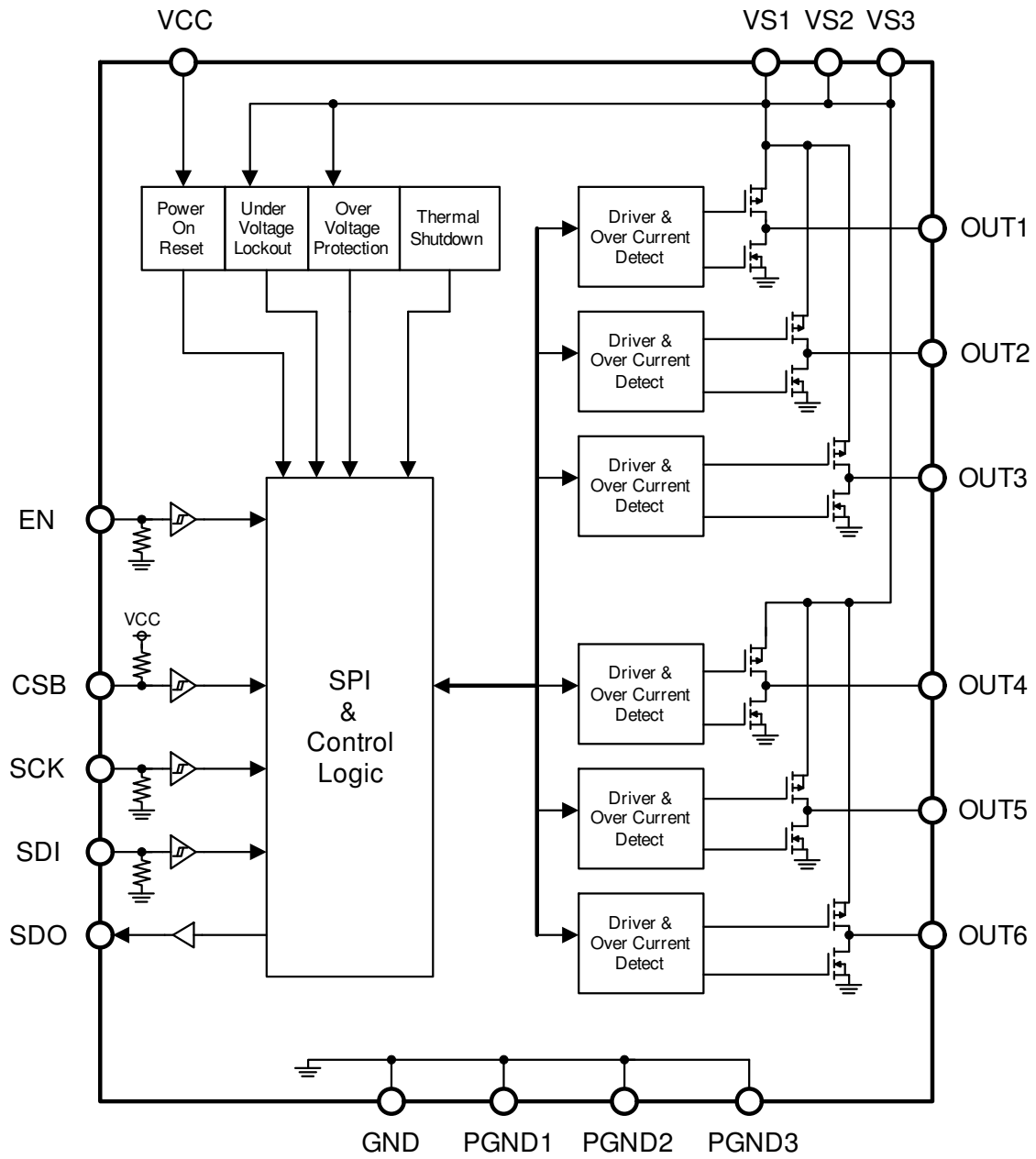


Figure 3. Block Diagram

## Absolute Maximum Ratings (Ta = 25°C)

Parameter	Symbol	Limit	Unit
Power supply voltage	$V_{VS1}, V_{VS2}, V_{VS3}$	-0.3 to +60	V
Driver supply voltage	$V_{CC}$	-0.3 to +7.0	V
Output voltage	$V_{OUT1}$ to $V_{OUT6}$	-0.3 to +60	V
Output current <sup>(Note 1)</sup>	$I_O$	1.0	A
Power dissipation <sup>(Note 2)</sup>	$P_d$	4.70	W
Logic input voltage	$V_{SDI}, V_{SCK}, V_{CSB}, V_{EN}$	-0.3 to $V_{CC}+0.3$	V
Logic output voltage	$V_{SDO}$	-0.3 to $V_{CC}+0.3$	V
SDO output current	$I_{SDO}$	5.0	mA
Operating temperature range	$T_{opr}$	-40 to +110	°C
Storage temperature range	$T_{stg}$	-55 to +150	°C
Junction temperature	$T_{jmax}$	150	°C

(Note 1)  $P_d$ , ASO should not be exceeded

(Note 2) Reduce 37.6mW per 1°C above 25°C (Mount on 4-layer 70.0mm x 70.0mm x 1.6mm board)

**Caution:** Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

## Recommended Operating Conditions (Ta=-40°C to +110°C)

Parameter	Symbol	Min	Typ	Max	Unit
Power supply voltage <sup>(Note 3)</sup>	$V_{VS1}, V_{VS2}, V_{VS3}$	8	12	36	V
Driver supply voltage <sup>(Note 3)</sup>	$V_{CC}$	4.5	5	5.5	V
Logic input voltage <sup>(Note 3)</sup>	$V_{EN}, V_{CSB}, V_{SCK}, V_{SDI}$	-0.3	+5	+5.5	V

(Note 3) In order to start operation, apply the voltage to VCC (Driver supply voltage) after VS (Power supply voltage) exceeds the minimum operating voltage range (8V).

In order to start operation, apply the voltage to Logic input voltage after VCC (Driver supply voltage) exceeds the minimum operating voltage range (4.5V).

**Electrical Characteristics** (Unless otherwise specified,  $V_{VS1}$ ,  $V_{VS2}$ ,  $V_{VS3} = 8V$  to  $36V$ ,  
 $V_{CC} = 4.5V$  to  $5.5V$ ,  $T_a = -40^{\circ}C$  to  $+110^{\circ}C$ )

Parameter	Symbol	Specification			Unit	Conditions
		Min	Typ	Max		
<b>Circuit Current</b>						
VS1to3 Circuit current1	$I_{VCC1}$	-	0	10	$\mu A$	EN=Low
VS1to3 Circuit current 2	$I_{VCC2}$	-	3.5	14	mA	
VCC Circuit current 1	$I_{VCC1}$	-	0	10	$\mu A$	EN=Low
VCC Circuit current 2	$I_{VCC2}$	-	5	9	mA	
<b>Output Characteristics</b>						
Output ON resistance high side 1	$R_{ONH1}$	-	1.25	2.0	$\Omega$	$I_o = 0.1A$ to $0.8A$ , $T_a = -40^{\circ}C$ to $+25^{\circ}C$
Output ON resistance high side 2	$R_{ONH2}$	-	2.0	2.55	$\Omega$	$I_o = 0.1A$ to $0.8A$ , $T_a = 25^{\circ}C$ to $110^{\circ}C$
Output ON resistance low side 1	$R_{ONL1}$	-	0.85	1.35	$\Omega$	$I_o = 0.1A$ to $0.8A$ , $T_a = -40^{\circ}C$ to $+25^{\circ}C$
Output ON resistance low side 2	$R_{ONL2}$	-	1.3	1.7	$\Omega$	$I_o = 0.1A$ to $0.8A$ , $T_a = 25^{\circ}C$ to $110^{\circ}C$
Output leakage high side	$I_{LH}$	-	0	10	$\mu A$	OUT1 to OUT6 = $0.0V$
Output leakage low side	$I_{LL}$	-	0	10	$\mu A$	OUT1 to OUT6 = $V_{VS1} = V_{VS2} = V_{VS3}$
Output diode voltage high side	$V_{FH}$	0.2	0.9	1.4	V	$I_F = 0.6A$
Output diode voltage low side	$V_{FL}$	0.2	0.9	1.4	V	$I_F = 0.6A$
<b>Serial Input Characteristics</b>						
Input high voltage	$V_{IH}$	$V_{CC} \times 0.6$	-	-	V	
Input low voltage	$V_{IL}$	-	-	$V_{CC} \times 0.2$	V	
Input high current 1	$I_{IH1}$	-	50	100	$\mu A$	$V_{CC} = SDI, SCK, EN = 5.0V$
Input high current 2	$I_{IH2}$	-	0	10	$\mu A$	$V_{CC} = CSB = 5.0V$
Input low current 1	$I_{IL1}$	-	0	10	$\mu A$	$SDI, SCK, EN = 0.0V$
Input low current 2	$I_{IL2}$	-	50	100	$\mu A$	$CSB = 0.0V, V_{CC}=5V$
<b>Serial Output Characteristics</b>						
Output high voltage	$V_{OH}$	$V_{CC}-0.6$	-	-	V	$I_{OH}=-1.0mA$
Output low voltage	$V_{OL}$	-	-	0.6	V	$I_{OH}=1.0mA$
<b>Protections</b>						
VS1to3 Under voltage detection	$V_{UVD}$	4.1	4.6	5.1	V	
VS1to3 Under voltage hysteresis	$V_{UVHYS}$	0.3	0.5	0.7	V	
VS1to3 Over voltage detection	$V_{OVP}$	45	50	55	V	
VS1to3 Over voltage hysteresis	$V_{OVPHYS}$	3	5	7	V	
Over current detection	$I_{OCD}$	1.05	1.5	1.95	A	
Over current detection delay time	$T_{DELAY}$	10	25	50	$\mu s$	
Thermal shutdown <sup>(Note 1)</sup>	$T_{TSD}$	150	175	200	$^{\circ}C$	
Thermal shutdown hysteresis <sup>(Note 1)</sup>	$T_{TSDHYS}$	-	25	-	$^{\circ}C$	

(Note 1) Design guaranteed. Not tested at outgoing.

Electrical Characteristics (Unless otherwise specified,  $V_{VS1}, V_{VS2}, V_{VS3} = 8V$  to  $36V$ ,  
 $V_{CC} = 4.5V$  to  $5.5V$ ,  $T_a = -40^{\circ}C$  to  $+110^{\circ}C$ )

Parameter	Symbol	Specification			Unit	Conditions
		Min	Typ	Max		
<b>Driver Output Timing</b>						
High side turn on time	$t_{tonLH}$	-	-	33.0	$\mu s$	$V_{VS1} = V_{VS2} = V_{VS3} = 12V$ , $R_{LOAD} = Open$
Low side turn on time	$t_{tonHL}$	-	-	33.0	$\mu s$	$V_{VS1} = V_{VS2} = V_{VS3} = 12V$ , $R_{LOAD} = Open$
OUT rise time	$t_{LHR}$	-	1.0	8.0	$\mu s$	$V_{VS1} = V_{VS2} = V_{VS3} = 12V$ , $R_{LOAD} = Open$
OUT fall time	$t_{HLF}$	-	1.0	8.0	$\mu s$	$V_{VS1} = V_{VS2} = V_{VS3} = 12V$ , $R_{LOAD} = Open$

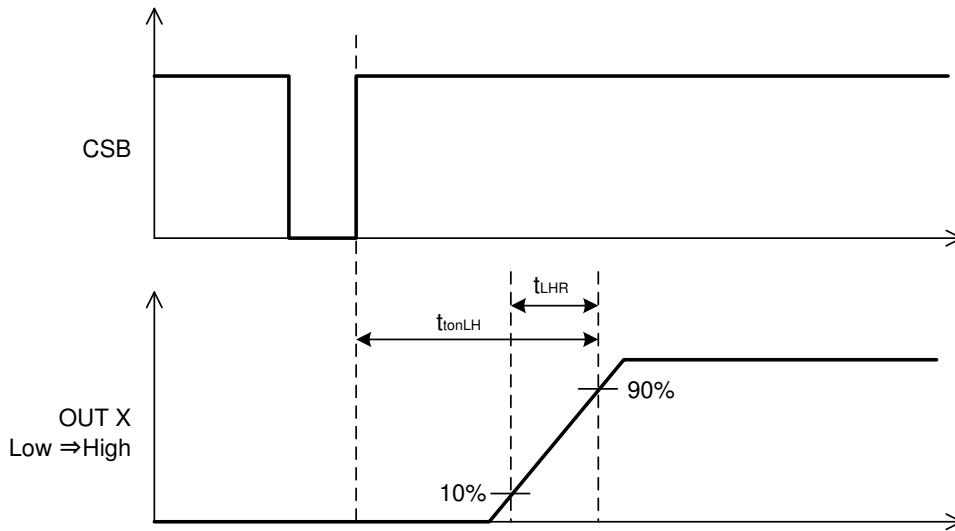


Figure 4. Driver Output Timing ( Low⇒High)

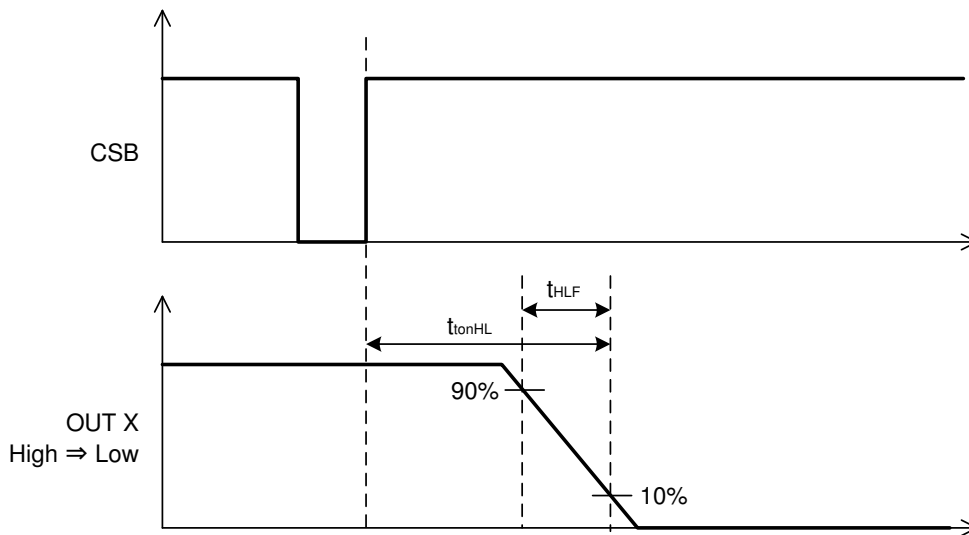
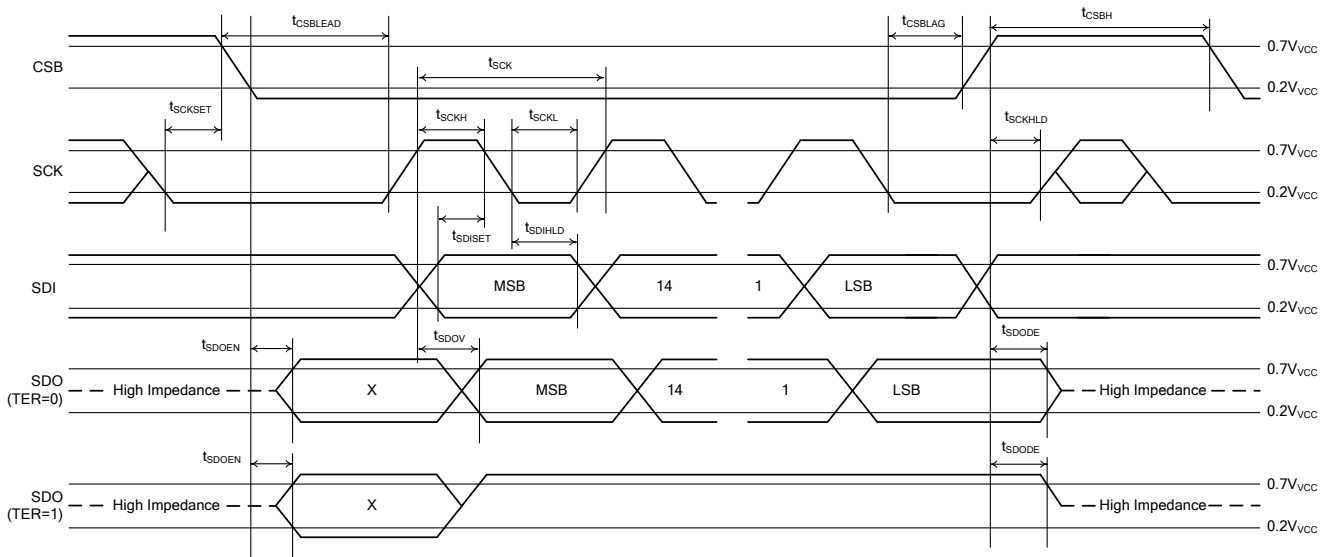


Figure 5. Driver Output Timing ( High⇒Low)

Electrical Characteristics (Unless otherwise specified,  $V_{VS1}, V_{VS2}, V_{VS3} = 8V$  to  $36V$ ,

$V_{CC} = 4.5V$  to  $5.5V$ ,  $T_a = -40^{\circ}C$  to  $+110^{\circ}C$ )

Parameter	Symbol	Specification			Unit	Conditions
		Min	Typ	Max		
SCK frequency	$f_{SCK}$	-	-	1	MHz	
SCK period	$t_{SCK}$	1000	-	-	ns	
SCK high time	$t_{SCKH}$	250	-	-	ns	
SCK low time	$t_{SCKL}$	250	-	-	ns	
SCK setup time	$t_{SCKSET}$	250	-	-	ns	
SCK hold time	$t_{SCKHLD}$	250	-	-	ns	
CSB lead time	$t_{CSBLEAD}$	500	-	-	ns	
CSB lag time	$t_{CSBLAG}$	500	-	-	ns	
CSB high time	$t_{CSBH}$	20	-	-	$\mu s$	
SDI setup time	$t_{SDISET}$	200	-	-	ns	
SDI hold time	$t_{SDIHLD}$	200	-	-	ns	
SDO valid time	$t_{SDOV}$	-	-	250	ns	
SDO enable after CSB falling edge	$t_{SDOEN}$	-	-	500	ns	
SDO disable after CSB rising edge	$t_{SDODE}$	-	-	500	ns	



X : Unstable state  
 TER (Internal Signal) : " 0 " in normal operation / " 1 " in detecting erroneous SPI transmission

Figure 6. Serial Interface Timing

**Typical Performance Curves**

(Unless otherwise specified,  $V_{VS1}, V_{VS2}, V_{VS3} = 8V$  to  $36V$ ,  $T_a = -40^{\circ}C$  to  $+110^{\circ}C$ )

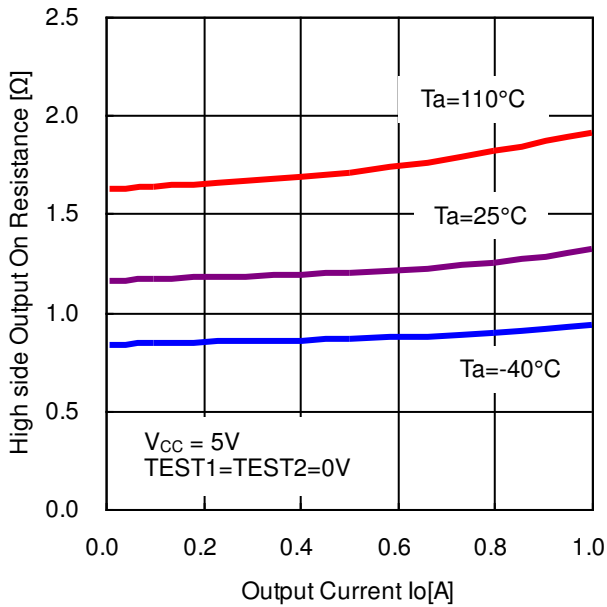


Figure 7. Output On Resistance vs Output Current (Output ON Resistance High Side,  $V_{VS}=12V$ )

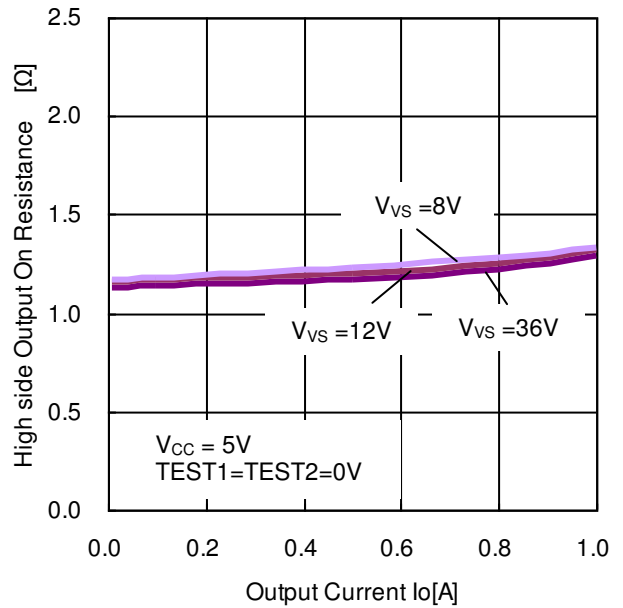


Figure 8. Output On Resistance vs Output Current (Output ON Resistance High Side,  $T_a=25^{\circ}C$ )

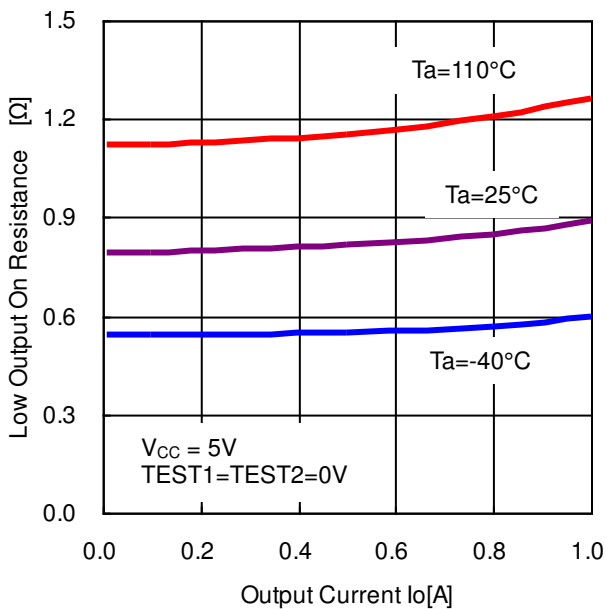


Figure 9. Output On Resistance vs Output Current (Output ON Resistance Low Side,  $V_{VS}=12V$ )

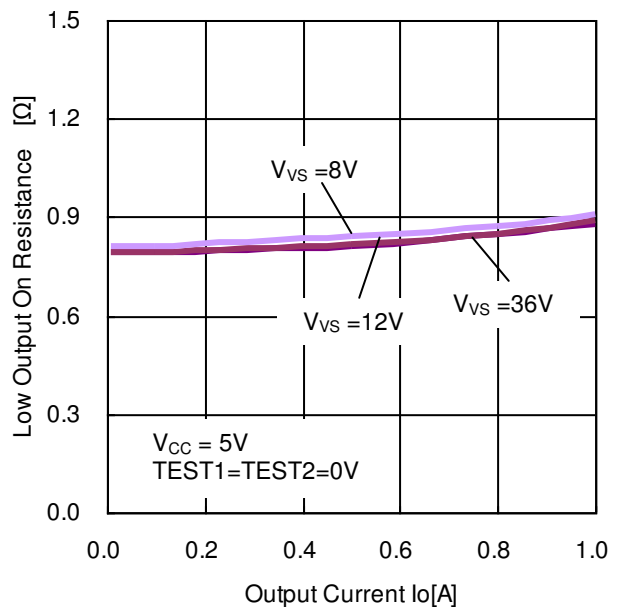


Figure 10. Output On Resistance vs Output Current (Output ON Resistance Low Side,  $T_a=25^{\circ}C$ )



Operation of Each Block

1. Serial Peripheral Interface: SPI

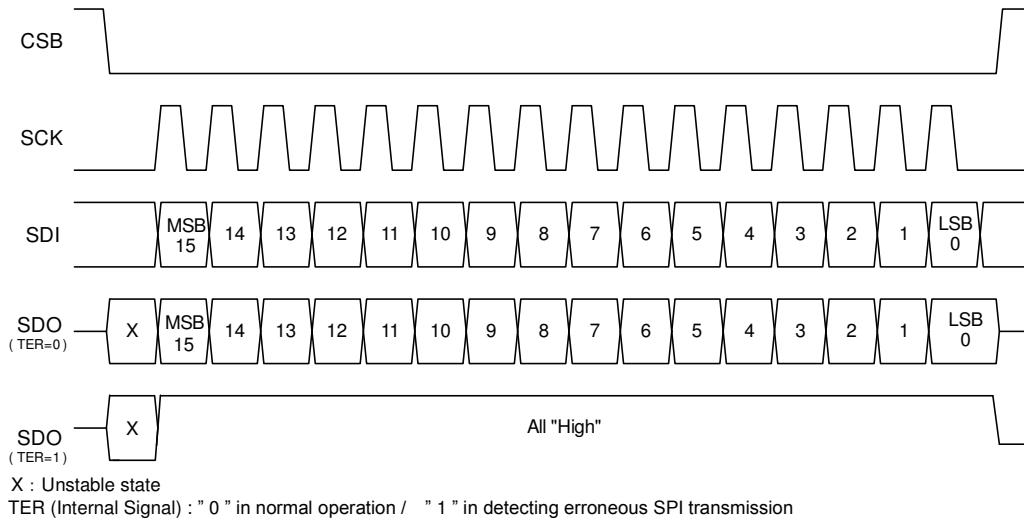


Figure11:SPI Communication Format

16bit serial interface is equipped to control ON / OFF of driver and various protections as well as to read out the state of protections. Input / Output register and its functions are described below.

(1) Input Data Register

Bit Number	Name	Description	Bit Status	Initial Value
15	SRR	Status Reset Register ( This bit is self clear )	0 : Normal 1 : Reset	0
14	HSC1	Control High side 1	0 : High side Off 1 : High side On	0
13	LSC1	Control Low side 1	0 : Low side Off 1 : Low side On	0
12	HSC2	Control High side 2	0 : High side Off 1 : High side On	0
11	LSC2	Control Low side 2	0 : Low side Off 1 : Low side On	0
10	HSC3	Control High side 3	0 : High side Off 1 : High side On	0
9	LSC3	Control Low side 3	0 : Low side Off 1 : Low side On	0
8	HSC4	Control High side 4	0 : High side Off 1 : High side On	0
7	LSC4	Control Low side 4	0 : Low side Off 1 : Low side On	0
6	HSC5	Control High side 5	0 : High side Off 1 : High side On	0
5	LSC5	Control Low side 5	0 : Low side Off 1 : Low side On	0
4	HSC6	Control High side 6	0 : High side Off 1 : High side On	0
3	LSC6	Control Low side 6	0 : Low side Off 1 : Low side On	0
2	TSDSTH	TSDS Register Mode	0 : Latch 1 : Through	0
1	PSSTH	OVPS / UVLOS Register Mode	0 : Latch 1 : Through	0
0	RESERVE	RESERVE	0 : Normal 1 : Prohibit	0

Input of High Side ON and Low Side ON via SPI control is prohibited. The input f High Side ON and Low Side ON results in High Side OFF and Low Side OFF state.

Daisy chain is not recommended due to its reliability concern. Connect Chip Select (CSB) to each device and run by SPI parallel control instead.

## (2) Output Data Register

Bit Number	Name	Description	Bit Status	Initial Value <sup>(Note 1)</sup>
15	OCDS	Over Current Detection Status	0 : Normal 1 : Fault	1 <sup>(Note 1)</sup>
14	HSS1	High side 1 Status	0 : High side Off 1 : High side On	0
13	LSS1	Low side 1 Status	0 : Low side Off 1 : Low side On	0
12	HSS2	High side 2 Status	0 : High side Off 1 : High side On	0
11	LSS2	Low side 2 Status	0 : Low side Off 1 : Low side On	0
10	HSS3	High side 3 Status	0 : High side Off 1 : High side On	0
9	LSS3	Low side 3 Status	0 : Low side Off 1 : Low side On	0
8	HSS4	High side 4 Status	0 : High side Off 1 : High side On	0
7	LSS4	Low side 4 Status	0 : Low side Off 1 : Low side On	0
6	HSS5	High side 5 Status	0 : High side Off 1 : High side On	0
5	LSS5	Low side 5 Status	0 : Low side Off 1 : Low side On	0
4	HSS6	High side 6 Status	0 : High side Off 1 : High side On	0
3	LSS6	Low side 6 Status	0 : Low side Off 1 : Low side On	0
2	TSDS	Thermal Shutdown Status	0 : Normal 1 : Fault	1 <sup>(Note 1)</sup>
1	OVPS	Over Voltage Protection Status	0 : Normal 1 : Fault	1 <sup>(Note 1)</sup>
0	UVLOS	UVLO ( VS ) Status	0 : Normal 1 : Fault	1 <sup>(Note 1)</sup>

(Note 1): Default is " 1 ( Fault ) ". Set SRR register " 1 " before use and reset the values.

Either Latch or Self Recovery are selectable on UVLOS, OVPS and TSDS error output registers. Only Latch is available on OCDS error output register.

< PSSTH , TSDSTH >	Under Voltage Lock Out UVLOS	Over Voltage Protection OVPS	Thermal Shut Down TSDS	Over Current Detection OCDS
< 0 , 0 >	Latch	Latch	Latch	Latch
< 0 , 1 >	Latch	Latch	Self Recovery	Latch
< 1 , 0 >	Self Recovery	Self Recovery	Latch	Latch
< 1 , 1 >	Self Recovery	Self Recovery	Self Recovery	Latch

Refer to the explanations of Protection Functions as far as OUT 1 to 6 operations are concerned.

## (3) Erroneous SPI Transmission (Transmission Error : TER)

When SCK inputs high pulse of 16, 24, 32, ... (8+8xN values) while CSB is low, erroneous SPI transmission is detected. If the error is detected, OUT1 to 6 outputs High Impedance and each error output register (OCDS, TSDS, OVPS and UVLOS) maintains the prior status accordingly. At the same time, if the CSB High period ( $t_{CSBH}$ ) goes below the specified 20 $\mu$ s, an erroneous SPI transmission can be detected. The transmission error status is refreshed every time CSB rises.

TER (Internal Signal) : " 0 " in normal operation / " 1 " in detecting erroneous SPI transmission

**2. Over Voltage Protection (OVP)**

All outputs run into High impedance when VS1 to 3 terminal voltage goes up to or above 50V (Typ). OVPS register is set "1" in this case. The outputs come back when VS1 to 3 terminal voltage goes down to or below 45V (Typ) and return to the normal operation. The state of output data register OVPS can be either Latch or Self Recovery depending on the state of input data register PSSTH. Input data register PSSTH=0 and output data register OPVS=1 for Latch. Input data register PSSTH=1 and output data register OVPS for Self Recovery when VS1 to 3 terminal voltage goes down to or below 45V (Typ). OVP doesn't operate when EN terminal is at Low level. Be sure not to exceed the absolute maximum power supply voltage to avoid the IC being destructed.

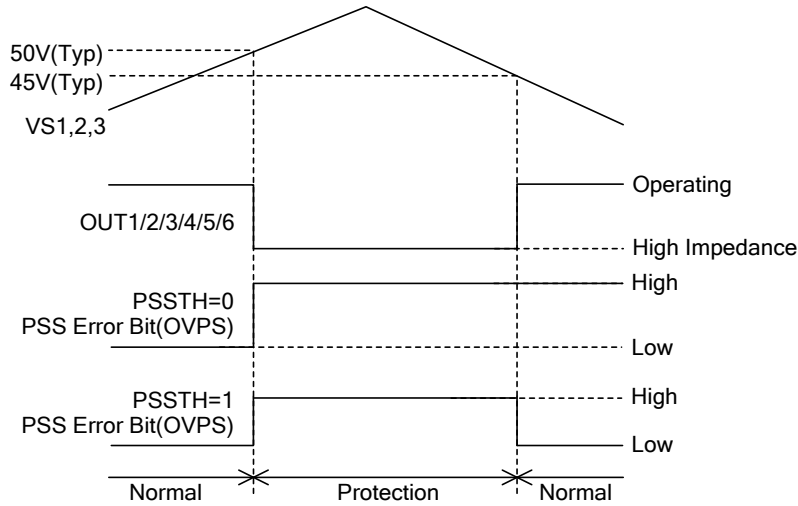


Figure 12. OVP Timing Chart

**3. Under Voltage Lock Out (UVLO)**

All outputs run into High impedance when VS1 to 3 terminal voltage goes down to or below 4.6V (Typ). UVLOS register is set "1" in this case. Outputs come back when VS1 to 3 terminal voltage goes up to or above 5.1V (Typ) and return to the normal operation mode. Output data register UVLOS in this case can be either Latch or Self Recovery depending on the status of input data register PSSTH. Input data register PSSTH=0 and output data register UVLOS= 1 for Latch. Input data register PSSTH=1 and output data register UVLOS for Self Recovery when VS1 to 3 terminal voltage goes up to or above 5.1V (Typ).

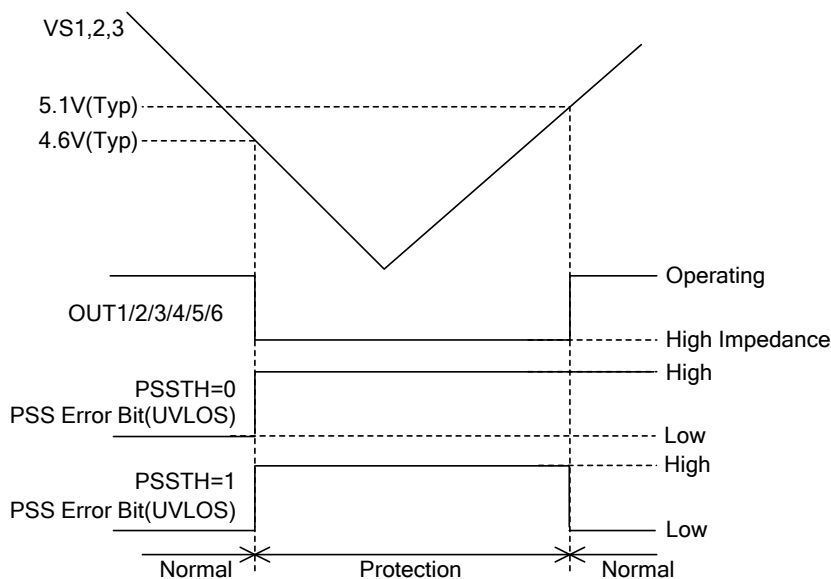


Figure 13. UVLO Timing Chart

4. Over Current Detection (OCD)

When 1.5A (Typ) current flows into the output terminal, overcurrent is detected and OCDS register is set "1". Only the Overcurrent Detected output stage is latched at High impedance. In order to release the latch in this case, it has to be reset via SRR register or EN terminal. Also 25µs (Typ) delay time is programmed to avoid the malfunction caused by noise.

OCD is the function to protect the IC from destruction caused by output short. However, the continuous overcurrent condition could lead the IC heating up or degraded and thus an appropriate measure has to be taken such as placing the IC into stand-by mode by application when overcurrent condition continues.

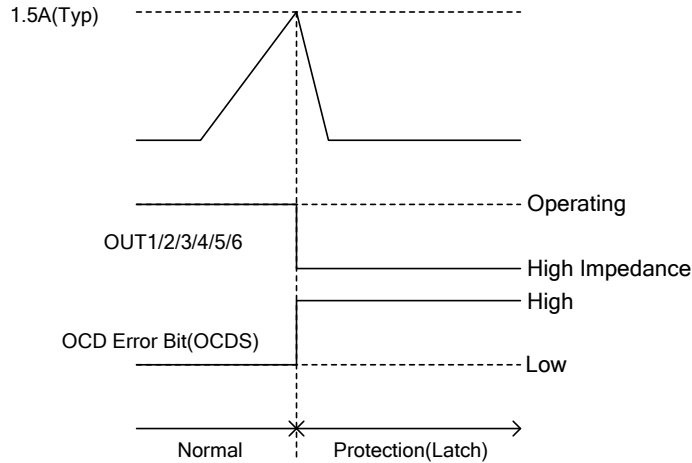


Figure 14. OCD Timing Chart

5. Thermal Shut Down (TSD)

When junction temperature goes up to or above 175°C (Typ), all outputs turn into High impedance. TSDS register is set "1" in this case.

Self Recovery kicks in when the junction temperature goes down to or below 150°C (Typ) and outputs come back and return to the normal operation. TSDS register in this case is maintained at "1". Output data register TSDS can be either Latch or Self Recovery depending on the input data register TSDSTH status. Input data register TSDSTH=0 and output data register TSDS=1 for latch. Input data register TSDSTH=1 and output data register TSDS for Self Recovery when the junction temperature goes down to or below 150°C (Typ).

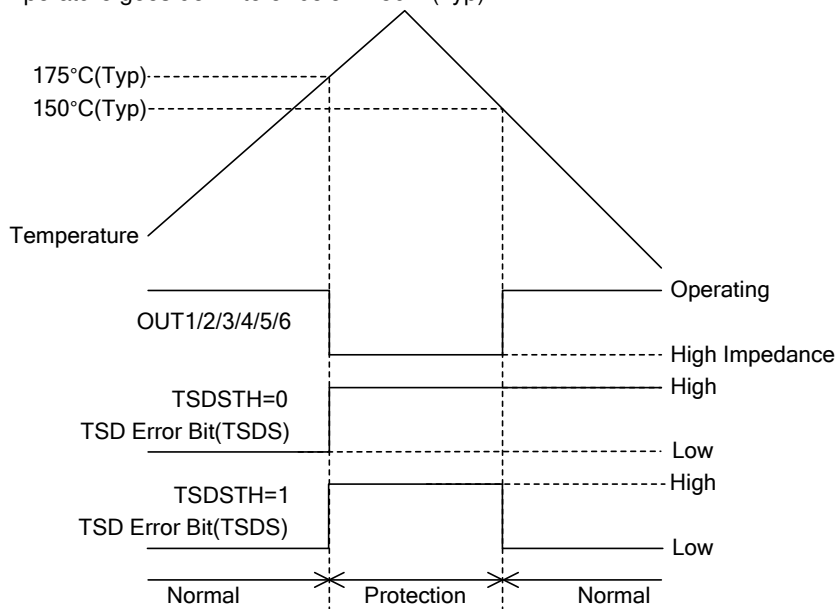
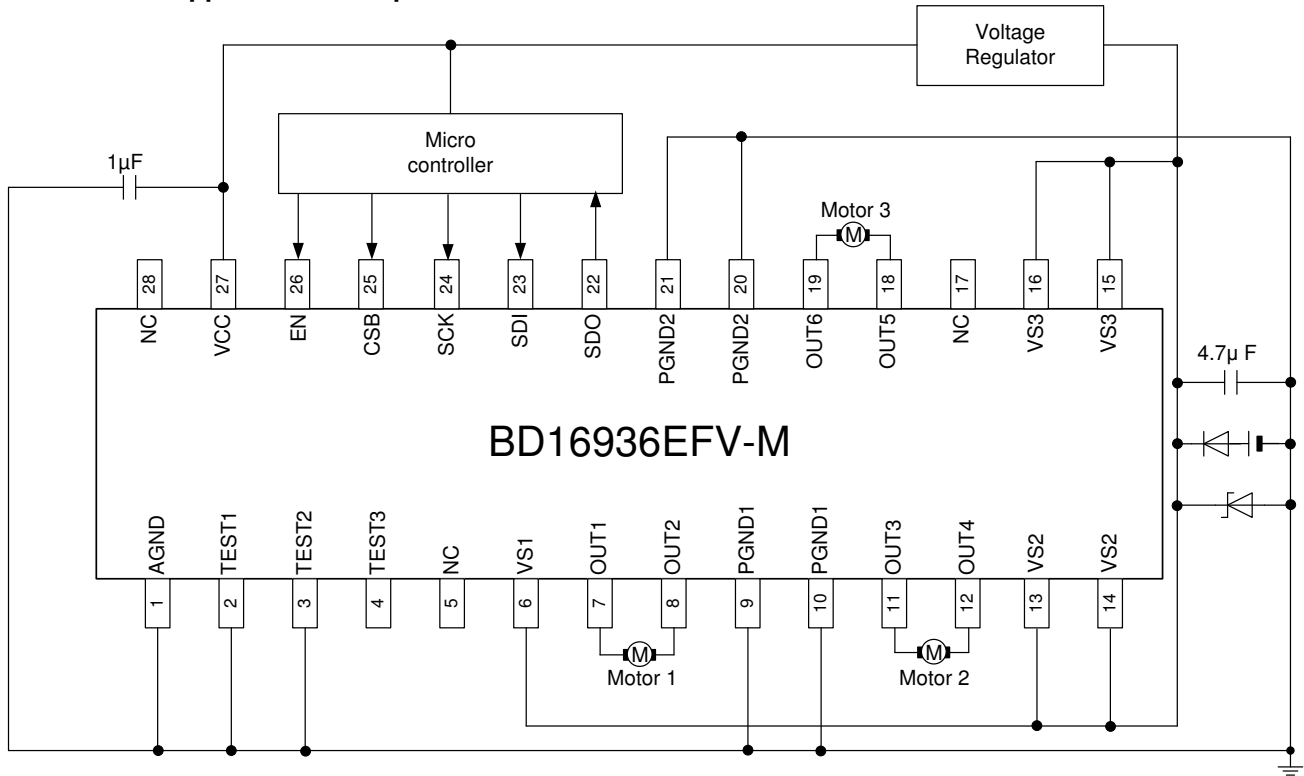


Figure 15. TSD Timing Chart

Recommended Application Example



The external circuit constants shown in the diagram above represent a recommended value, respectively.

Figure 16. Recommended Application Example

Cautions on Designing of Application Circuits

1. Applicable Motors

Be noted that The BD16936EFV-M motor driver can only drive DC motors and cannot drive stepping motors.

2. VS1, VS2, VS3 and VCC

Be sure to mount a power supply capacitor in the vicinity of the IC pins between the VS and PGND and between the VCC and GND. Determine the capacitance of the capacitor after fully ensuring that it presents no problems in characteristics. ( The recommended value of between VS and PGND is 4.7µF or more. The recommended value of between VCC and GND is 1.0µF or more.)

Furthermore, cause a short circuit between VS1, VS2 and VS3 (set them to the same potential) before using the IC.

3. Counter-Electromotive Force

The counter-electromotive force may vary with operating conditions and environment, and individual motor characteristics. Fully ensure that the counter-electromotive force presents no problems in the operation or the IC.

4. Fluctuations in Output Pin Voltage

If any output pin makes a significant fluctuation in the voltage to fall below GND potential due to heat generation conditions, power supply, and motor to be used, or other conditions, this may result in malfunctions or other failures. In such cases, take appropriate measures, including the addition of a Schottky diode between the output pin and ground.

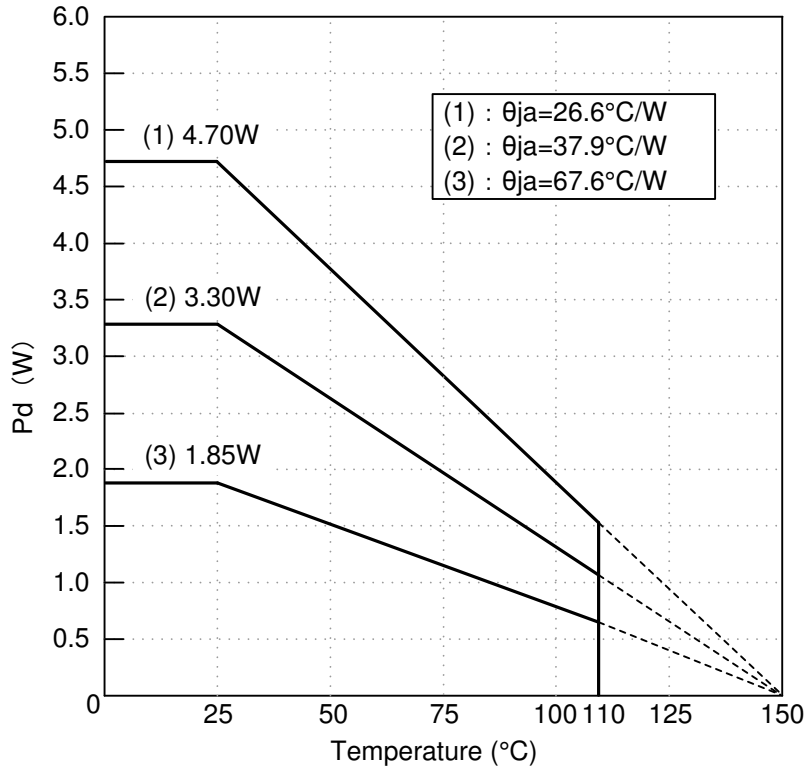
5. Rush Current

This IC has no built-in circuit that limits rush currents caused by applying current to the power supply or switching operation mode. To avoid the rush currents, take physical measures such as adding a current-limiting resistor between VS1, VS2 and VS3 pins and the power supply.

6. Thermal Pad

Since a thermal pad is connected to the sub side of this IC, connect it to the ground potential. Furthermore, do not use the thermal pad as ground interconnect.

Power Dissipation



- (1): ROHM standard board (70.0[mm] × 70.0[mm] × 1.6[mm], Glass Epoxy Board 4 layer, Copper foil area 70×70[mm])
- (2): ROHM standard board (70.0[mm] × 70.0[mm] × 1.6[mm], Glass Epoxy Board 2 layer, Copper foil area 70×70[mm])
- (3): ROHM standard board (70.0[mm] × 70.0[mm] × 1.6[mm], Glass Epoxy Board 2 layer, Copper foil area 15×15[mm])

Figure 17. BD16936EFV-M Power Dissipation

I/O equivalent circuits

Pin No.	Pin Name	I/O Equivalence Circuit
2 3 23 24 26	TEST1 TEST2 SDI SCK EN	
4	TEST3	
7 8 11 12 18 19	OUT1 OUT2 OUT3 OUT4 OUT5 OUT6	
22	SDO	
25	CSB	

Resistance values shown in the diagrams above represent a typical limit, respectively.

## Operational Notes

### 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

### 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

### 3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

### 4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

### 5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

### 6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

### 7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

### 8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

### 9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

### 10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.



**Operational Notes - continued**

**11. Unused Input Pins**

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

**12. Regarding the Input Pin of the IC**

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When  $GND > Pin A$  and  $GND > Pin B$ , the P-N junction operates as a parasitic diode.  
 When  $GND > Pin B$ , the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

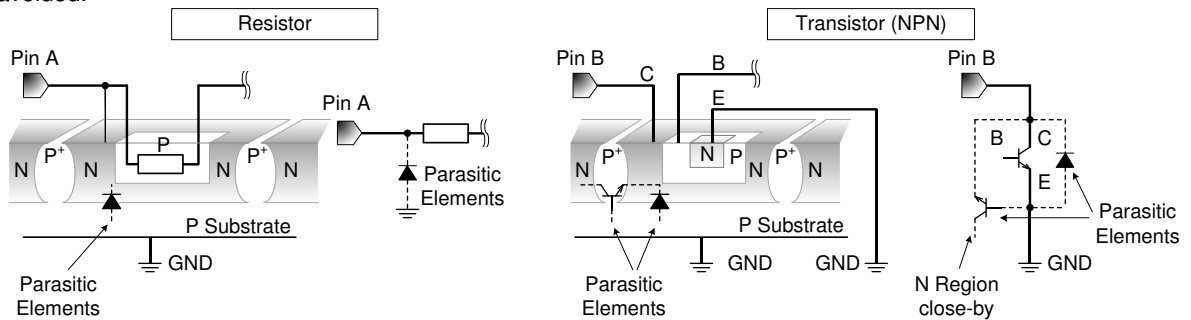


Figure 18. Example of monolithic IC structure

**13. Ceramic Capacitor**

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

**14. Area of Safe Operation (ASO)**

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

**15. Thermal Shutdown Circuit(TSD)**

This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature ( $T_j$ ) will rise which will activate the TSD circuit that will turn OFF all output pins. When the  $T_j$  falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

**16. Over Current Protection Circuit (OCP)**

This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.

Ordering Information

B D 1 6 9 3 6 E F V

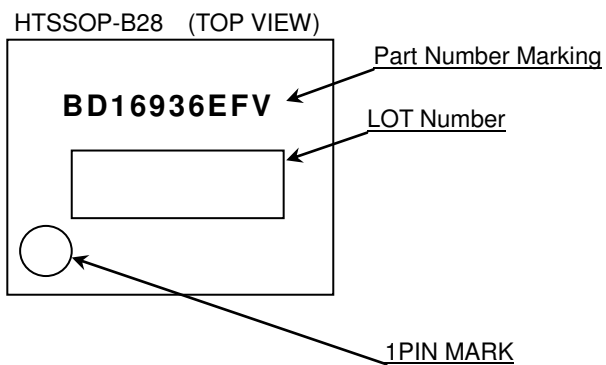
ME 2

Part Number

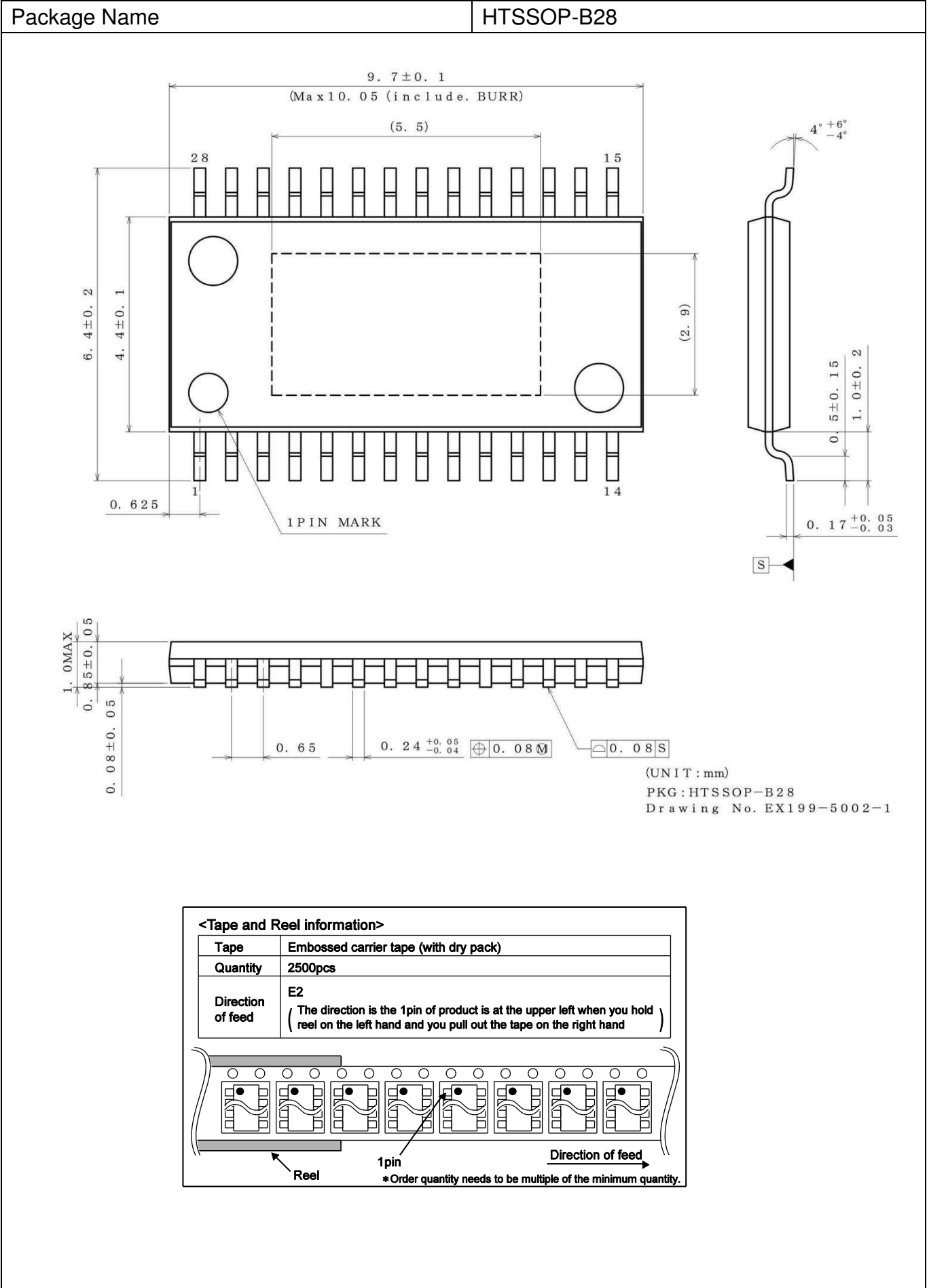
Package  
EFV: HTSSOP-B28

Packing and Forming Specification  
M: Automotive Grade  
E2: Embossed Tape and Reel

Marking Diagrams



Physical Dimension, Tape and Reel Information



**Revision History**

Date	Revision	Changes
18.Dec.2013	001	New Release
19.Jun.2015	002	P1 Note1,2 add comment P2,5,4,10 repair Note number All Update latest format

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JAPAN	USA	EU	CHINA
CLASS III	CLASS III	CLASS II b	CLASS III
CLASS IV		CLASS III	

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  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
4. The Products are not subject to radiation-proof design.
5. Please verify and confirm characteristics of the final or mounted products in using the Products.
6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
8. Confirm that operation temperature is within the specified range described in the product specification.
9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

## Precaution for Mounting / Circuit board design

1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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**Precaution for Electrostatic**

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of ionizer, friction prevention and temperature / humidity control).

**Precaution for Storage / Transportation**

1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
  - [a] the Products are exposed to sea winds or corrosive gases, including Cl<sub>2</sub>, H<sub>2</sub>S, NH<sub>3</sub>, SO<sub>2</sub>, and NO<sub>2</sub>
  - [b] the temperature or humidity exceeds those recommended by ROHM
  - [c] the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
4. Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

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