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April ${ }^{\text {st }}, 2010$
Renesas Electronics Corporation

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## SOURCE DRIVER FOR 300/288-OUTPUT TFT-LCD

## DESCRIPTION

$\mu$ PD16782A is a source driver for TFT liquid crystal panels. This IC consists of a multiplexer circuit supporting a variety of pixel arrays, a shift register that generates sampling timing, and two sample and hold circuits that sample analog voltages. Because the two sample and hold circuits alternately execute sampling and holding, a high definition can be obtained.

Besides, according to the pixel arrangement of the LCD panel, it can respond to simultaneous sampling and successive sampling. It is ideal for a wide range of applications, including navigation systems and automobile LCDTVs.

## FEATURES

- Can be driven on 5 V (Dynamic range: 4.6 V , V DD2 $=5.0 \mathrm{~V}$ )
- 300/288-output
- fclk $=15 \mathrm{MHz}$ MAX. $(\mathrm{VdD} 1=3.0 \mathrm{~V})$
- Simultaneous/sequential sampling selectable according to pixel array

Simultaneous sampling: Vertical stripe
Sequential sampling: Vertical stripe, delta array, mosaic array

- Two sets of sample and hold circuits
- Stripe, delta, and mosaic pixel arrays supported by internal multiplexer circuit
- Left and right shift selected by R,/L pin
- COG mounting possible

Remark /xxx indicates active low signal.

## ORDERING INFORMATION

| Part Number | Package |
| :---: | :---: |
| $\mu$ PD16782AP | Chip |

Remark Purchasing the above chip entails the exchange of documents such as a separate memorandum or product quality, so please contact one of our sales representative.

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Not all products and/or types are available in every country. Please check with an NEC Electronics sales representative for availability and additional information.
^ 1. BLOCK DIAGRAM

2. SAMPLE AND HOLD CIRCUIT AND OUTPUT CIRCUIT


## 3. PIN CONFIGURATION


$\mu$ PD16782A

Table 3-1. Pad Coordinate (1/4)

| No. | Pad Name | X [ $\mu \mathrm{m}]$ | $\mathrm{Y}[\mu \mathrm{m}]$ | Bump Size (X:Y) [ $\mu \mathrm{m}$ | No. | Pad Name | $\mathrm{X}[\mu \mathrm{m}]$ | $\mathrm{Y}[\mu \mathrm{m}]$ | Bump Size (X:Y) [ $\mu \mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Dummy1 | -464.0 | 8451.0 | 100:60 | 56 | MP/TH | -464.0 | 378.6 | 100:60 |
| 2 | RMON1 | -464.0 | 8014.2 | 100:60 | 57 | MP/1.5 | -464.0 | 145.5 | 100:60 |
| 3 | RMON1 | -464.0 | 7842.0 | 100:60 | 58 | MP/1.5 | -464.0 | 65.5 | 100:60 |
| 4 | VDD2 | -464.0 | 7538.6 | 100:60 | 59 | MP/1.5 | -464.0 | -14.5 | 100:60 |
| 5 | VDD2 | -464.0 | 7458.6 | 100:60 | 60 | R,/L | -464.0 | -247.6 | 100:60 |
| 6 | VDD2 | -464.0 | 7378.6 | 100:60 | 61 | R,/L | -464.0 | -327.6 | 100:60 |
| 7 | VDD2 | -464.0 | 7298.6 | 100:60 | 62 | R,/L | -464.0 | -407.6 | 100:60 |
| 8 | VDD2 | -464.0 | 7218.6 | 100:60 | 63 | RESET | -464.0 | -640.7 | 100:60 |
| 9 | VDD2 | -464.0 | 7138.6 | 100:60 | 64 | RESET | -464.0 | -720.7 | 100:60 |
| 10 | VDD2 | -464.0 | 7058.6 | 100:60 | 65 | RESET | -464.0 | -800.7 | 100:60 |
| 11 | VDD2 | -464.0 | 6978.6 | 100:60 | 66 | INH | -464.0 | -1033.8 | 100:60 |
| 12 | VDD2 | -464.0 | 6898.6 | 100:60 | 67 | INH | -464.0 | -1113.8 | 100:60 |
| 13 | VDD2 | -464.0 | 6818.6 | 100:60 | 68 | INH | -464.0 | -1193.8 | 100:60 |
| 14 | VDD2 | -464.0 | 6738.6 | 100:60 | 69 | CLI1 | -464.0 | -1427.0 | 100:60 |
| 15 | VDD2 | -464.0 | 6658.6 | 100:60 | 70 | CLI1 | -464.0 | -1507.0 | 100:60 |
| 16 | V SS | -464.0 | 6181.0 | 100:60 | 71 | CLI1 | -464.0 | -1587.0 | 100:60 |
| 17 | $\mathrm{V}_{\text {SS1 }}$ | -464.0 | 6101.0 | 100:60 | 72 | CLI2 | -464.0 | -1820.1 | 100:60 |
| 18 | V $\mathrm{SS}^{1}$ | -464.0 | 6021.0 | 100:60 | 73 | CLI2 | -464.0 | -1900.1 | 100:60 |
| 19 | $\mathrm{V}_{\text {SS1 }}$ | -464.0 | 5941.0 | 100:60 | 74 | CLI2 | -464.0 | -1980.1 | 100:60 |
| 20 | Vss1 | -464.0 | 5861.0 | 100:60 | 75 | CLI3 | -464.0 | -2213.2 | 100:60 |
| 21 | V ${ }_{\text {SS1 }}$ | -464.0 | 5781.0 | 100:60 | 76 | CLI3 | -464.0 | -2293.2 | 100:60 |
| 22 | VSS1 | -464.0 | 5701.0 | 100:60 | 77 | CLI3 | -464.0 | -2373.2 | 100:60 |
| 23 | VDD1 | -464.0 | 5239.4 | 100:60 | 78 | TEST | -464.0 | -2606.3 | 100:60 |
| 24 | VDD1 | -464.0 | 5159.4 | 100:60 | 79 | TEST | -464.0 | -2686.3 | 100:60 |
| 25 | VDD1 | -464.0 | 5079.4 | 100:60 | 80 | TEST | -464.0 | -2766.3 | 100:60 |
| 26 | VDD1 | -464.0 | 4999.4 | 100:60 | 81 | STHR | -464.0 | -3227.0 | 100:60 |
| 27 | VDD1 | -464.0 | 4919.4 | 100:60 | 82 | STHR | -464.0 | -3307.0 | 100:60 |
| 28 | VDD1 | -464.0 | 4839.4 | 100:60 | 83 | STHR | -464.0 | -3387.0 | 100:60 |
| 29 | VDD1 | -464.0 | 4759.4 | 100:60 | 84 | STHR | -464.0 | -3467.0 | 100:60 |
| 30 | C1 | -464.0 | 4335.2 | 100:60 | 85 | STHR | -464.0 | -3547.0 | 100:60 |
| 31 | C1 | -464.0 | 4255.2 | 100:60 | 86 | STHR | -464.0 | -3627.0 | 100:60 |
| 32 | C1 | -464.0 | 4175.2 | 100:60 | 87 | Osel | -464.0 | -4170.4 | 100:60 |
| 33 | C1 | -464.0 | 4095.2 | 100:60 | 88 | Osel | -464.0 | -4250.4 | 100:60 |
| 34 | C1 | -464.0 | 4015.2 | 100:60 | 89 | Osel | -464.0 | -4330.4 | 100:60 |
| 35 | C1 | -464.0 | 3935.2 | 100:60 | 90 | VDD1 | -464.0 | -4759.4 | 100:60 |
| 36 | C2 | -464.0 | 3470.4 | 100:60 | 91 | VDD1 | -464.0 | -4839.4 | 100:60 |
| 37 | C2 | -464.0 | 3390.4 | 100:60 | 92 | VDD1 | -464.0 | -4919.4 | 100:60 |
| 38 | C2 | -464.0 | 3310.4 | 100:60 | 93 | VDD1 | -464.0 | -4999.4 | 100:60 |
| 39 | C2 | -464.0 | 3230.4 | 100:60 | 94 | VDD1 | -464.0 | -5079.4 | 100:60 |
| 40 | C2 | -464.0 | 3150.4 | 100:60 | 95 | VDD1 | -464.0 | -5159.4 | 100:60 |
| 41 | C2 | -464.0 | 3070.4 | 100:60 | 96 | VDD1 | -464.0 | -5239.4 | 100:60 |
| 42 | C3 | -464.0 | 2605.6 | 100:60 | 97 | VSS1 | -464.0 | -5701.0 | 100:60 |
| 43 | C3 | -464.0 | 2525.6 | 100:60 | 98 | Vss1 | -464.0 | -5781.0 | 100:60 |
| 44 | C3 | -464.0 | 2445.6 | 100:60 | 99 | Vss1 | -464.0 | -5861.0 | 100:60 |
| 45 | C3 | -464.0 | 2365.6 | 100:60 | 100 | V ${ }_{\text {SS1 }}$ | -464.0 | -5941.0 | 100:60 |
| 46 | C3 | -464.0 | 2285.6 | 100:60 | 101 | Vss1 | -464.0 | -6021.0 | 100:60 |
| 47 | C3 | -464.0 | 2205.6 | 100:60 | 102 | Vss1 | -464.0 | -6101.0 | 100:60 |
| 48 | STHL | -464.0 | 1384.2 | 100:60 | 103 | Vss1 | -464.0 | -6181.0 | 100:60 |
| 49 | STHL | -464.0 | 1304.2 | 100:60 | 104 | VDD2 | -464.0 | -6658.6 | 100:60 |
| 50 | STHL | -464.0 | 1224.2 | 100:60 | 105 | VDD2 | -464.0 | -6738.6 | 100:60 |
| 51 | STHL | -464.0 | 1144.2 | 100:60 | 106 | VDD2 | -464.0 | -6818.6 | 100:60 |
| 52 | STHL | -464.0 | 1064.2 | 100:60 | 107 | VDD2 | -464.0 | -6898.6 | 100:60 |
| 53 | STHL | -464.0 | 984.2 | 100:60 | 108 | VDD2 | -464.0 | -6978.6 | 100:60 |
| 54 | MP/TH | -464.0 | 538.6 | 100:60 | 109 | VDD2 | -464.0 | -7058.6 | 100:60 |
| 55 | MP/TH | -464.0 | 458.6 | 100:60 | 110 | VDD2 | -464.0 | -7138.6 | 100:60 |

$\mu$ PD16782A

Table 3-1. Pad Coordinate (2/4)

| No. | Pad Name | $\mathrm{X}[\mu \mathrm{m}]$ | $\mathrm{Y}[\mu \mathrm{m}]$ | Bump Size (X:Y) [ $\mu \mathrm{m}$ ] | No. | Pad Name | $\mathrm{X}[\mu \mathrm{m}]$ | $\mathrm{Y}[\mu \mathrm{m}]$ | Bump Size (X:Y) [ $\mu \mathrm{m}$ ] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 111 | VDD2 | -464.0 | -7218.6 | 100:60 | 166 | $\mathrm{S}_{37}$ | 402.0 | -6533.5 | 80:37 |
| 112 | VDD2 | -464.0 | -7298.6 | 100:60 | 167 | $\mathrm{S}_{38}$ | 402.0 | -6476.5 | 80:37 |
| 113 | VDD2 | -464.0 | -7378.6 | 100:60 | 168 | $\mathrm{S}_{39}$ | 402.0 | -6419.5 | 80:37 |
| 114 | VDD2 | -464.0 | -7458.6 | 100:60 | 169 | $\mathrm{S}_{40}$ | 402.0 | -6362.5 | 80:37 |
| 115 | VDD2 | -464.0 | -7538.6 | 100:60 | 170 | $\mathrm{S}_{41}$ | 402.0 | -6305.5 | 80:37 |
| 116 | RMON2 | -464.0 | -7842.0 | 100:60 | 171 | $\mathrm{S}_{42}$ | 402.0 | -6248.5 | 80:37 |
| 117 | RMON2 | -464.0 | -8014.2 | 100:60 | 172 | S43 | 402.0 | -6191.5 | 80:37 |
| 118 | Dummy2 | -464.0 | -8451.0 | 100:60 | 173 | S44 | 402.0 | -6134.5 | 80:37 |
| 119 | Vss2 | -399.8 | -8769.0 | 60100 | 174 | S45 | 402.0 | -6077.5 | 80:37 |
| 120 | $V_{\text {SS2 }}$ | -319.8 | -8769.0 | 60100 | 175 | $\mathrm{S}_{46}$ | 402.0 | -6020.5 | 80:37 |
| 121 | Vss2 | -239.8 | -8769.0 | 60100 | 176 | $\mathrm{S}_{47}$ | 402.0 | -5963.5 | 80:37 |
| 122 | $V_{\text {ss2 }}$ | -159.8 | -8769.0 | 60100 | 177 | $\mathrm{S}_{48}$ | 402.0 | -5906.5 | 80:37 |
| 123 | $V_{\text {ss2 }}$ | -79.8 | -8769.0 | 60100 | 178 | $\mathrm{S}_{49}$ | 402.0 | -5849.5 | 80:37 |
| 124 | Vss2 | 0.2 | -8769.0 | $60 \quad 100$ | 179 | S50 | 402.0 | -5792.5 | 80:37 |
| 125 | Vss2 | 80.2 | -8769.0 | 60100 | 180 | S51 | 402.0 | -5735.5 | 80:37 |
| 126 | Vss2 | 160.2 | -8769.0 | 60100 | 181 | S52 | 402.0 | -5678.5 | 80:37 |
| 127 | Vss2 | 240.2 | -8769.0 | $60 \quad 100$ | 182 | S53 | 402.0 | -5621.5 | 80:37 |
| 128 | Vss2 | 320.2 | -8769.0 | 60100 | 183 | S54 | 402.0 | -5564.5 | 80:37 |
| 129 | Dummy3 | 402.0 | -8642.5 | 80:37 | 184 | S55 | 402.0 | -5507.5 | 80:37 |
| 130 | $\mathrm{S}_{1}$ | 402.0 | -8585.5 | 80:37 | 185 | S56 | 402.0 | -5450.5 | 80:37 |
| 131 | $\mathrm{S}_{2}$ | 402.0 | -8528.5 | 80:37 | 186 | S57 | 402.0 | -5393.5 | 80:37 |
| 132 | $\mathrm{S}_{3}$ | 402.0 | -8471.5 | 80:37 | 187 | $\mathrm{S}_{58}$ | 402.0 | -5336.5 | 80:37 |
| 133 | $\mathrm{S}_{4}$ | 402.0 | -8414.5 | 80:37 | 188 | S59 | 402.0 | -5279.5 | 80:37 |
| 134 | S5 | 402.0 | -8357.5 | 80:37 | 189 | S60 | 402.0 | -5222.5 | 80:37 |
| 135 | S6 | 402.0 | -8300.5 | 80:37 | 190 | S61 | 402.0 | -5165.5 | 80:37 |
| 136 | $\mathrm{S}_{7}$ | 402.0 | -8243.5 | 80:37 | 191 | S62 | 402.0 | -5108.5 | 80:37 |
| 137 | S8 | 402.0 | -8186.5 | 80:37 | 192 | S63 | 402.0 | -5051.5 | 80:37 |
| 138 | S9 | 402.0 | -8129.5 | 80:37 | 193 | S64 | 402.0 | -4994.5 | 80:37 |
| 139 | S10 | 402.0 | -8072.5 | 80:37 | 194 | S65 | 402.0 | -4937.5 | 80:37 |
| 140 | $\mathrm{S}_{11}$ | 402.0 | -8015.5 | 80:37 | 195 | S66 | 402.0 | -4880.5 | 80:37 |
| 141 | $\mathrm{S}_{12}$ | 402.0 | -7958.5 | 80:37 | 196 | S67 | 402.0 | -4823.5 | 80:37 |
| 142 | $\mathrm{S}_{13}$ | 402.0 | -7901.5 | 80:37 | 197 | $\mathrm{S}_{68}$ | 402.0 | -4766.5 | 80:37 |
| 143 | $\mathrm{S}_{14}$ | 402.0 | -7844.5 | 80:37 | 198 | S69 | 402.0 | -4709.5 | 80:37 |
| 144 | $\mathrm{S}_{15}$ | 402.0 | -7787.5 | 80:37 | 199 | S70 | 402.0 | -4652.5 | 80:37 |
| 145 | $\mathrm{S}_{16}$ | 402.0 | -7730.5 | 80:37 | 200 | S71 | 402.0 | -4595.5 | 80:37 |
| 146 | S 17 | 402.0 | -7673.5 | 80:37 | 201 | S72 | 402.0 | -4538.5 | 80:37 |
| 147 | $\mathrm{S}_{18}$ | 402.0 | -7616.5 | 80:37 | 202 | S73 | 402.0 | -4481.5 | 80:37 |
| 148 | $\mathrm{S}_{19}$ | 402.0 | -7559.5 | 80:37 | 203 | S74 | 402.0 | -4424.5 | 80:37 |
| 149 | $\mathrm{S}_{20}$ | 402.0 | -7502.5 | 80:37 | 204 | S75 | 402.0 | -4367.5 | 80:37 |
| 150 | $\mathrm{S}_{21}$ | 402.0 | -7445.5 | 80:37 | 205 | S76 | 402.0 | -4310.5 | 80:37 |
| 151 | $\mathrm{S}_{22}$ | 402.0 | -7388.5 | 80:37 | 206 | $\mathrm{S}_{77}$ | 402.0 | -4253.5 | 80:37 |
| 152 | $\mathrm{S}_{23}$ | 402.0 | -7331.5 | 80:37 | 207 | $\mathrm{S}_{78}$ | 402.0 | -4196.5 | 80:37 |
| 153 | $\mathrm{S}_{24}$ | 402.0 | -7274.5 | 80:37 | 208 | S79 | 402.0 | -4139.5 | 80:37 |
| 154 | $\mathrm{S}_{25}$ | 402.0 | -7217.5 | 80:37 | 209 | S80 | 402.0 | -4082.5 | 80:37 |
| 155 | $\mathrm{S}_{26}$ | 402.0 | -7160.5 | 80:37 | 210 | S81 | 402.0 | -4025.5 | 80:37 |
| 156 | $\mathrm{S}_{27}$ | 402.0 | -7103.5 | 80:37 | 211 | S82 | 402.0 | -3968.5 | 80:37 |
| 157 | $\mathrm{S}_{28}$ | 402.0 | -7046.5 | 80:37 | 212 | S83 | 402.0 | -3911.5 | 80:37 |
| 158 | $\mathrm{S}_{29}$ | 402.0 | -6989.5 | 80:37 | 213 | $\mathrm{S}_{84}$ | 402.0 | -3854.5 | 80:37 |
| 159 | $\mathrm{S}_{30}$ | 402.0 | -6932.5 | 80:37 | 214 | S85 | 402.0 | -3797.5 | 80:37 |
| 160 | $\mathrm{S}_{31}$ | 402.0 | -6875.5 | 80:37 | 215 | S86 | 402.0 | -3740.5 | 80:37 |
| 161 | $\mathrm{S}_{32}$ | 402.0 | -6818.5 | 80:37 | 216 | $\mathrm{S}_{87}$ | 402.0 | -3683.5 | 80:37 |
| 162 | $\mathrm{S}_{33}$ | 402.0 | -6761.5 | 80:37 | 217 | S88 | 402.0 | -3626.5 | 80:37 |
| 163 | $\mathrm{S}_{34}$ | 402.0 | -6704.5 | 80:37 | 218 | S89 | 402.0 | -3569.5 | 80:37 |
| 164 | $\mathrm{S}_{35}$ | 402.0 | -6647.5 | 80:37 | 219 | S90 | 402.0 | -3512.5 | 80:37 |
| 165 | $\mathrm{S}_{36}$ | 402.0 | -6590.5 | 80:37 | 220 | S91 | 402.0 | -3455.5 | 80:37 |

Table 3-1. Pad Coordinate (3/4)

| No. | Pad Name | $\mathrm{X}[\mu \mathrm{m}]$ | $\mathrm{Y}[\mu \mathrm{m}]$ | Bump Size (X:Y) [ $\mu \mathrm{m}$ ] | No. | Pad Name | $\mathrm{X}[\mu \mathrm{m}]$ | Y [ $\mu \mathrm{m}$ ] | Bump Size (X:Y) [ $\mu \mathrm{m}$ ] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 221 | $\mathrm{S}_{92}$ | 402.0 | -3398.5 | 80:37 | 276 | $\mathrm{S}_{147}$ | 402.0 | -263.5 | 80:37 |
| 222 | S93 | 402.0 | -3341.5 | 80:37 | 277 | $\mathrm{S}_{148}$ | 402.0 | -206.5 | 80:37 |
| 223 | $\mathrm{S}_{94}$ | 402.0 | -3284.5 | 80:37 | 278 | $\mathrm{S}_{149}$ | 402.0 | -149.5 | 80:37 |
| 224 | S95 | 402.0 | -3227.5 | 80:37 | 279 | $\mathrm{S}_{150}$ | 402.0 | -92.5 | 80:37 |
| 225 | S96 | 402.0 | -3170.5 | 80:37 | 280 | $\mathrm{S}_{151}$ | 402.0 | -35.5 | 80:37 |
| 226 | S97 | 402.0 | -3113.5 | 80:37 | 281 | $\mathrm{S}_{152}$ | 402.0 | 21.5 | 80:37 |
| 227 | S98 | 402.0 | -3056.5 | 80:37 | 282 | S153 | 402.0 | 78.5 | 80:37 |
| 228 | S99 | 402.0 | -2999.5 | 80:37 | 283 | $\mathrm{S}_{154}$ | 402.0 | 135.5 | 80:37 |
| 229 | $\mathrm{S}_{100}$ | 402.0 | -2942.5 | 80:37 | 284 | $\mathrm{S}_{155}$ | 402.0 | 192.5 | 80:37 |
| 230 | $\mathrm{S}_{101}$ | 402.0 | -2885.5 | 80:37 | 285 | $\mathrm{S}_{156}$ | 402.0 | 249.5 | 80:37 |
| 231 | $\mathrm{S}_{102}$ | 402.0 | -2828.5 | 80:37 | 286 | $\mathrm{S}_{157}$ | 402.0 | 306.5 | 80:37 |
| 232 | $\mathrm{S}_{103}$ | 402.0 | -2771.5 | 80:37 | 287 | $\mathrm{S}_{158}$ | 402.0 | 363.5 | 80:37 |
| 233 | $\mathrm{S}_{104}$ | 402.0 | -2714.5 | 80:37 | 288 | $\mathrm{S}_{159}$ | 402.0 | 420.5 | 80:37 |
| 234 | $\mathrm{S}_{105}$ | 402.0 | -2657.5 | 80:37 | 289 | S160 | 402.0 | 477.5 | 80:37 |
| 235 | $\mathrm{S}_{106}$ | 402.0 | -2600.5 | 80:37 | 290 | $\mathrm{S}_{161}$ | 402.0 | 534.5 | 80:37 |
| 236 | $\mathrm{S}_{107}$ | 402.0 | -2543.5 | 80:37 | 291 | $\mathrm{S}_{162}$ | 402.0 | 591.5 | 80:37 |
| 237 | S 108 | 402.0 | -2486.5 | 80:37 | 292 | $\mathrm{S}_{163}$ | 402.0 | 648.5 | 80:37 |
| 238 | $\mathrm{S}_{109}$ | 402.0 | -2429.5 | 80:37 | 293 | S164 | 402.0 | 705.5 | 80:37 |
| 239 | $\mathrm{S}_{110}$ | 402.0 | -2372.5 | 80:37 | 294 | $\mathrm{S}_{165}$ | 402.0 | 762.5 | 80:37 |
| 240 | $\mathrm{S}_{111}$ | 402.0 | -2315.5 | 80:37 | 295 | $\mathrm{S}_{166}$ | 402.0 | 819.5 | 80:37 |
| 241 | $\mathrm{S}_{112}$ | 402.0 | -2285.5 | 80:37 | 296 | $\mathrm{S}_{167}$ | 402.0 | 876.5 | 80:37 |
| 242 | $\mathrm{S}_{113}$ | 402.0 | -2201.5 | 80:37 | 297 | $\mathrm{S}_{168}$ | 402.0 | 933.5 | 80:37 |
| 243 | $\mathrm{S}_{114}$ | 402.0 | -2144.5 | 80:37 | 298 | $\mathrm{S}_{169}$ | 402.0 | 990.5 | 80:37 |
| 244 | $\mathrm{S}_{115}$ | 402.0 | -2087.5 | 80:37 | 299 | S 170 | 402.0 | 1047.5 | 80:37 |
| 245 | $\mathrm{S}_{116}$ | 402.0 | -2030.5 | 80:37 | 300 | S 171 | 402.0 | 1104.5 | 80:37 |
| 246 | $\mathrm{S}_{117}$ | 402.0 | -1973.5 | 80:37 | 301 | S 172 | 402.0 | 1161.5 | 80:37 |
| 247 | $\mathrm{S}_{118}$ | 402.0 | -1916.5 | 80:37 | 302 | S 173 | 402.0 | 1218.5 | 80:37 |
| 248 | $\mathrm{S}_{119}$ | 402.0 | -1859.5 | 80:37 | 303 | S 174 | 402.0 | 1275.5 | 80:37 |
| 249 | $\mathrm{S}_{120}$ | 402.0 | -1802.5 | 80:37 | 304 | S 175 | 402.0 | 1332.5 | 80:37 |
| 250 | $\mathrm{S}_{121}$ | 402.0 | -1745.5 | 80:37 | 305 | S 176 | 402.0 | 1389.5 | 80:37 |
| 251 | $\mathrm{S}_{122}$ | 402.0 | -1688.5 | 80:37 | 306 | S 177 | 402.0 | 1446.5 | 80:37 |
| 252 | $\mathrm{S}_{123}$ | 402.0 | -1631.5 | 80:37 | 307 | S 178 | 402.0 | 1503.5 | 80:37 |
| 253 | $\mathrm{S}_{124}$ | 402.0 | -1574.5 | 80:37 | 308 | S 179 | 402.0 | 1560.5 | 80:37 |
| 254 | $\mathrm{S}_{125}$ | 402.0 | -1517.5 | 80:37 | 309 | S 180 | 402.0 | 1617.5 | 80:37 |
| 255 | $\mathrm{S}_{126}$ | 402.0 | -1460.5 | 80:37 | 310 | $\mathrm{S}_{181}$ | 402.0 | 1674.5 | 80:37 |
| 256 | $\mathrm{S}_{127}$ | 402.0 | -1403.5 | 80:37 | 311 | $\mathrm{S}_{182}$ | 402.0 | 1731.5 | 80:37 |
| 257 | $\mathrm{S}_{128}$ | 402.0 | -1346.5 | 80:37 | 312 | $\mathrm{S}_{183}$ | 402.0 | 1788.5 | 80:37 |
| 258 | $\mathrm{S}_{129}$ | 402.0 | -1289.5 | 80:37 | 313 | $\mathrm{S}_{184}$ | 402.0 | 1845.5 | 80:37 |
| 259 | $\mathrm{S}_{130}$ | 402.0 | -1232.5 | 80:37 | 314 | $\mathrm{S}_{185}$ | 402.0 | 1902.5 | 80:37 |
| 260 | $\mathrm{S}_{131}$ | 402.0 | -1175.5 | 80:37 | 315 | $\mathrm{S}_{186}$ | 402.0 | 1959.5 | 80:37 |
| 261 | $\mathrm{S}_{132}$ | 402.0 | -1118.5 | 80:37 | 316 | $\mathrm{S}_{187}$ | 402.0 | 2016.5 | 80:37 |
| 262 | $\mathrm{S}_{133}$ | 402.0 | -1061.5 | 80:37 | 317 | $\mathrm{S}_{188}$ | 402.0 | 2073.5 | 80:37 |
| 263 | $\mathrm{S}_{134}$ | 402.0 | -1004.5 | 80:37 | 318 | $\mathrm{S}_{189}$ | 402.0 | 2130.5 | 80:37 |
| 264 | $\mathrm{S}_{135}$ | 402.0 | -947.5 | 80:37 | 319 | $\mathrm{S}_{190}$ | 402.0 | 2187.5 | 80:37 |
| 265 | $\mathrm{S}_{136}$ | 402.0 | -890.5 | 80:37 | 320 | S191 | 402.0 | 2244.5 | 80:37 |
| 266 | $\mathrm{S}_{137}$ | 402.0 | -833.5 | 80:37 | 321 | S 192 | 402.0 | 2301.5 | 80:37 |
| 267 | $\mathrm{S}_{138}$ | 402.0 | -776.5 | 80:37 | 322 | S193 | 402.0 | 2358.5 | 80:37 |
| 268 | $\mathrm{S}_{139}$ | 402.0 | -719.5 | 80:37 | 323 | $\mathrm{S}_{194}$ | 402.0 | 2415.5 | 80:37 |
| 269 | $\mathrm{S}_{140}$ | 402.0 | -662.5 | 80:37 | 324 | S 195 | 402.0 | 2472.5 | 80:37 |
| 270 | $\mathrm{S}_{141}$ | 402.0 | -605.5 | 80:37 | 325 | $\mathrm{S}_{196}$ | 402.0 | 2529.5 | 80:37 |
| 271 | $\mathrm{S}_{142}$ | 402.0 | -548.5 | 80:37 | 326 | $\mathrm{S}_{197}$ | 402.0 | 2586.5 | 80:37 |
| 272 | $\mathrm{S}_{143}$ | 402.0 | -491.5 | 80:37 | 327 | $\mathrm{S}_{198}$ | 402.0 | 2643.5 | 80:37 |
| 273 | $\mathrm{S}_{144}$ | 402.0 | -434.5 | 80:37 | 328 | S199 | 402.0 | 2700.5 | 80:37 |
| 274 | $\mathrm{S}_{145}$ | 402.0 | -377.5 | 80:37 | 329 | S200 | 402.0 | 2757.5 | 80:37 |
| 275 | $\mathrm{S}_{146}$ | 402.0 | -320.5 | 80:37 | 330 | S201 | 402.0 | 2814.5 | 80:37 |

Table 3-1. Pad Coordinate (4/4)


## Bump specs (standard reference value)

| Parameter | Specifications |
| :--- | :---: |
| Bump size tolerance | $\pm 5 \mu \mathrm{~m}$ |
| Bump height (design center value) | $17 \mu \mathrm{~m}$ |
| Bump height tolerance (within lot) | $\pm 4 \mu \mathrm{~m}$ |
| Bump height tolerance (within chip) | Range: $3 \mu \mathrm{~m}$ |
| Bump hardness | $50 \pm 20 \mathrm{Hv}$ |

## ^ 4. PIN FUNCTIONS

| Symbol | Pin Name | Pad No. | 1/O | Description |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| C1 to C3 | Video signal | 30, 47 | Input | Input R, G, and B video signals. |  |  |
| $\mathrm{S}_{1}$ to $\mathrm{S}_{300}$ | Video signal | 130 to 429 | Output | Video signal output pins. Video signals which are sampled and held, are output to these pins during horizontal period. |  |  |
| STHR, STHL | Cascade | $\begin{aligned} & 81 \text { to } 86, \\ & 48 \text { to } 53 \end{aligned}$ | I/O | Start pulse I/O pins of sample hold timing. <br> In the case of right shift, STHR becomes an input pin and STHL becomes an output pin. <br> In the case of left shift, STHL becomes an input pin and STHR becomes an output pin. |  |  |
| CLI1 to CLI3 | Shift clock | 69 to 77 | Input | A start pulse is read at the rising edge of CLI1. Sampling pulse SHPn is generated at the rising edge of CLI1 to CLI3 in the sequential sampling mode, and at the rising edge of CLI1 in the simultaneous sampling mode (for details, refer to 5.1.5 <br> Relation between Shift Clock CLIn and Internal Sampling Pulse SHPn). |  |  |
| INH | Inhibit | 66 to 68 | Input | At the falling edge of INH , it is done that the change of Multiplexer circuits and the conversion of 2 sets of Sample and Hold circuits. |  |  |
| RESET | Reset | 63 to 65 | Input | Resets the select counter of the multiplexer and the selector circuit of the two sample and hold circuits during RESET=H. After reset, the multiplexer is turned OFF, so sure to input one pulse of the INH signal before inputting the video signal. If the video signal is input without the INH signal, sampling is not executed. |  |  |
| MP/TH | Multiplexer circuit select (1) | 54 to 56 | Input | In the combination of MP/TH and MP/1.5, it can support to the following modes. |  |  |
|  |  |  |  | In the combination of MP/TH and MP/1.5, it can sup | MP/TH | MP/1.5 |
|  |  |  |  |  | L | L |
| MP/1.5 | Multiplexer circuit select (2) | 57 to 59 | Input | Vertical stripe array (Sequential sampling) | L | H |
|  |  |  |  | Mosaic array | H | L |
|  |  |  |  | Double-side delta array | H | H |
| R,/L | Shift direction select | 60 to 62 | Input | $\begin{aligned} & \mathrm{R}, / \mathrm{L}=\mathrm{H}: \text { Right shift: } \mathrm{STHR} \rightarrow \mathrm{~S}_{1} \rightarrow \mathrm{~S}_{300} \rightarrow \mathrm{STHL} \\ & \mathrm{R}, / \mathrm{L}=\mathrm{L}: \text { Left shift: } \mathrm{STHL} \rightarrow \mathrm{~S}_{300} \rightarrow \mathrm{~S}_{1} \rightarrow \mathrm{STHR} \end{aligned}$ |  |  |
| Osel | Selection of number of outputs switching | 87 to 89 | Input | Selects number of outputs. <br> Osel = L: 288 output mode <br> Osel $=\mathrm{H}: 300$ output mode <br> Output pins S145 to S156 are invalid in 288 output mode. When Osel=L, the output signals of S145 to S156 become same as S157 to S168 (R,/L = H) or S133 to S144 ( $\mathrm{R}, / \mathrm{L}=\mathrm{L}$ ). |  |  |
| RMON1, RMON2 | Monitor | $\begin{aligned} & 2,3,116, \\ & 117 \end{aligned}$ | - | This pin can measure the connection resistance at the time of COG mounting. RMON1 and RMON2 are each short inside IC. <br> It does not connect with other pins inside IC. |  |  |
| Dummy1 to Dummy4 | Dummy | $\begin{aligned} & 1,118, \\ & 129,430 \\ & \hline \end{aligned}$ | - | No dummy pins are connected with other pins inside IC. |  |  |
| VdD1 | Logic power supply | $\begin{aligned} & 23 \text { to } 29, \\ & 90 \text { to } 96 \\ & \hline \end{aligned}$ | - | 3.0 to 5.5 V |  |  |
| VdD2 | Driver power supply | $\begin{aligned} & 4 \text { to } 15, \\ & 104 \text { to } 115 \end{aligned}$ | - | $5.0 \pm 0.5 \mathrm{~V}$ |  |  |
| Vss1 | Logic ground | $\begin{aligned} & 16 \text { to } 22, \\ & 97 \text { to } 103 \end{aligned}$ | - | Connect this pin to ground of system. |  |  |
| Vss2 | Driver ground | $\begin{aligned} & 119 \text { to } 128, \\ & 431 \text { to } 440 \\ & \hline \end{aligned}$ | - | Connect this pin to ground of system. |  |  |
| TEST | Test | 78 to 80 | - | Fix this pin to low level. |  |  |

## 5. FUNCTIONAL DESCRIPTION

### 5.1 Multiplexer Circuit

This circuit selects RGB video signals input to the C1 to C3 pins according to the pixel array of the liquid crystal panel, and outputs the signals to the $\mathrm{S}_{1} \sim \mathrm{~S}_{300}$ pins.
Vertical stripe array(Simultaneous sampling/Sequential sampling), double-side delta array (Sequential sampling), or mosaic array (Sequential sampling) can be selected by using the MP/TH and MP/1.5 pins.

### 5.1.1 Vertical stripe array mode (Simultaneous sampling) (MP/TH = L, MP/1.5 = L)

In this mode, the relation between video signals C1 to C3, and output pins is as shown below. This mode is used to drive a panel of vertical stripe array. In this mode, the multiplexer circuit is in the through status.

Please input the shift clock only to CL1 pin, and fix CL2 and CL3 pin to low level.
Refer to 5.1.5 Relation between Shift Clock CLIn and Internal Sampling Pulse SHPn.

Table 5-1. Relation between Video Signals C1 to C3, and Output Pins (during right shift)

| Line No. (number of INHs ) | RESET | INH | $\mathrm{S}_{1}\left(\mathrm{~S}_{300}\right)$ | S2 (S299) | $\mathrm{S}_{3}\left(\mathrm{~S}_{298}\right)$ | $\mathrm{S}_{4}\left(\mathrm{~S}_{297}\right)$ | ... | S299 (S2) | $\mathrm{S}_{300}\left(\mathrm{~S}_{1}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | H | L | Sampling <br> C1 (C3) | Sampling C2 (C2) | Sampling C3 (C1) | Sampling C1 (C3) | $\ldots$ | Sampling C2 (C2) | Sampling C3 (C1) |
| 1 | L | $\downarrow$ | Output <br> C1 (C3) | Output <br> C2 (C2) | Output <br> C3 (C1) | Output <br> C1 (C3) | ... | $\begin{gathered} \text { Output } \\ \text { C2 (C2) } \\ \hline \end{gathered}$ | Output <br> C3 (C1) |
| 2 | L | $\downarrow$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \\ & \hline \end{aligned}$ | Output <br> C2 (C2) | Output <br> C3 (C1) | Output <br> C1 (C3) | ... | Output <br> C2 (C2) | Output <br> C3 (C1) |
| 3 | L | $\downarrow$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | $\begin{gathered} \text { Output } \\ \text { C2 (C2) } \\ \hline \end{gathered}$ | Output <br> C3 (C1) | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \\ & \hline \end{aligned}$ | ... | Output <br> C2 (C2) | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \\ & \hline \end{aligned}$ |
| : | : | : | : | : | : | : | ... | : | : |

Remark () indicates the case of left shift.

Figure 5-1. Pixel Arrangement of Vertical Stripe Array and Multiplexer Operation


Figure 5-2. Timing Chart of Vertical Stripe Array


### 5.1.2 Vertical stripe array mode (sequential sampling) (MP/TH = L, MP/1.5 = H)

Please input the shift clock to CL1, CL2 and CL3 pin.
Refer to 5.1.5 Relation between Shift Clock CLIn and Internal Sampling Pulse SHPn.

Table 5-2. Relation between Video Signals C1 to C3, and Output Pins (during right shift)

| Line No. (number of INHs) | RESET | INH | $\mathrm{S}_{1}\left(\mathrm{~S}_{300}\right)$ | $\mathrm{S}_{2}\left(\mathrm{~S}_{299}\right)$ | $\mathrm{S}_{3}\left(\mathrm{~S}_{298}\right)$ | $\mathrm{S}_{4}\left(\mathrm{~S}_{297}\right)$ | ... | $\mathrm{S}_{299}\left(\mathrm{~S}_{2}\right)$ | $\mathrm{S}_{300}\left(\mathrm{~S}_{1}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | H | L | Sampling C1 (C3) | Sampling C2 (C2) | Sampling C3 (C1) | Sampling C1 (C3) | ... | Sampling C2 (C2) | Sampling C3 (C1) |
| 1 | L | $\downarrow$ | Output <br> C1 (C3) | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ |
| 2 | L | $\downarrow$ | Output <br> C1 (C3) | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | Output <br> C3 (C1) | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \\ & \hline \end{aligned}$ | Output C3 (C1) |
| 3 | L | $\downarrow$ | Output <br> C1 (C3) | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ |
| : | : | : | : | : | : | : | ... | : | : |

Remark ( ) indicates the case of left shift.

Figure 5-3. Pixel Arrangement of Vertical Stripe Array and Multiplexer Operation


Figure 5-4. Timing Chart of Vertical Stripe Array


### 5.1.3 Double-side delta array mode (MP/TH = H, MP/1.5 = H)

Table 5-3. Relation between Video Signals C1 to C3 and Output Pins

| Line No. (number of INHs) | RESET | INH | $\mathrm{S}_{1}\left(\mathrm{~S}_{300}\right)$ | $\mathrm{S} 2(\mathrm{~S} 299)$ | $\mathrm{S}_{3}\left(\mathrm{~S}_{298}\right)$ | $\mathrm{S}_{4}\left(\mathrm{~S}_{297}\right)$ | ... | S299 (S2) | $\mathrm{S}_{300}\left(\mathrm{~S}_{1}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | H | L | Undefined | Undefined | Undefined | Undefined | $\ldots$ | Undefined | Undefined |
| 1 | L | $\downarrow$ | Sampling C2 (C3) | $\begin{gathered} \text { Sampling } \\ \text { C3 (C2) } \\ \hline \end{gathered}$ | Sampling <br> C1 (C1) | Sampling C2 (C3) | ... | Sampling $\mathrm{C} 3 \text { (C2) }$ | Sampling C1 (C1) |
| 2 | L | $\downarrow$ | Output <br> C2 (C3) | $\begin{aligned} & \text { Output } \\ & \text { C3 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C2 (C3) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C3 (C2) } \end{aligned}$ | Output |
| 3 | L | $\downarrow$ | Output <br> C1 (C1) | Output <br> C2 (C3) | Output <br> C3 (C2) | Output <br> C1 (C1) | ... | Output <br> C2 (C3) | Output C3 (C2) |
| 4 | L | $\downarrow$ | Output <br> C2 (C3) | $\begin{aligned} & \text { Output } \\ & \text { C3 (C2) } \end{aligned}$ | Output <br> C1 (C1) | $\begin{aligned} & \text { Output } \\ & \text { C2 (C3) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C3 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C1) } \end{aligned}$ |
| 5 | L | $\downarrow$ | Output <br> C1 (C1) | $\begin{aligned} & \text { Output } \\ & \text { C2 (C3) } \\ & \hline \end{aligned}$ | Output <br> C3 (C2) | Output <br> C1 (C1) | $\ldots$ | Output $\mathrm{C} 2(\mathrm{C} 3)$ | Output <br> C3 (C2) |
| : | : | : | : | : | : | : | ... | : | : |

Remark () indicates the case of left shift.

Figure 5-5. Pixel Arrangement of Double-Side Delta Array and Multiplexer Operation


Figure 5-6. Timing Chart of Both-Sides Delta Array


### 5.1.4 Mosaic array mode (MP/TH = H, MP/1.5 = L)

Table 5-4. Relation between Video Signals C1 to C3, and Output Pins

| Line No. (number of INHs) | RESET | INH | $\mathrm{S}_{1}\left(\mathrm{~S}_{300}\right)$ | S2 (S299) | $\mathrm{S}_{3}\left(\mathrm{~S}_{298}\right)$ | $\mathrm{S}_{4}\left(\mathrm{~S}_{297}\right)$ | ... | $\mathrm{S}_{299}\left(\mathrm{~S}_{2}\right)$ | $\mathrm{S}_{300}\left(\mathrm{~S}_{1}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | H | L | Undefined | Undefined | Undefined | Undefined | $\ldots$ | Undefined | Undefined |
| 1 | L | $\downarrow$ | $\begin{gathered} \text { Sampling } \\ \text { C1 (C3) } \\ \hline \end{gathered}$ | Sampling C2 (C2) | Sampling C3 (C1) | $\begin{gathered} \text { Sampling } \\ \text { C1 (C3) } \\ \hline \end{gathered}$ | ... | Sampling C2 (C2) | Sampling C3 (C1) |
| 2 | L | $\downarrow$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ | Output <br> C1 (C3) | ... | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ |
| 3 | L | $\downarrow$ | $\begin{gathered} \text { Output } \\ \text { C3 (C2) } \\ \hline \end{gathered}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C2 (C3) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C2) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C1 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C2 (C3) } \\ & \hline \end{aligned}$ |
| 4 | L | $\downarrow$ | $\begin{aligned} & \text { Output } \\ & \text { C2 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C3) } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C2) } \end{aligned}$ | Output C2 (C1) | $\ldots$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C3) } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C2) } \end{aligned}$ |
| 5 | L | $\downarrow$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C1 (C3) } \end{aligned}$ | ... | $\begin{aligned} & \text { Output } \\ & \text { C2 (C2) } \\ & \hline \end{aligned}$ | $\begin{aligned} & \text { Output } \\ & \text { C3 (C1) } \end{aligned}$ |
| : | : | : | : | : | : | : | ... | : | : |

Remark ( ) indicates the case of left shift.
Figure 5-7. Pixel Arrangement of Mosaic Array and Multiplexer Operation


Figure 5-8. Timing Chart of Mosaic Array


### 5.1.5 Relation between Shift Clock CLIn and Internal Sampling Pulse SHPn

(1) Simultaneous sampling ( ( ) indicates the case of left shift.)


Remark C1 through C3 are sampled while SHPn is high level.
(2) Sequential sampling ( ( ) indicates the case of left shift.)


Remarks 1. Input a three-phase clock to shift clock pins CLI1 to CLI3.
2. The video signals ( C 1 to C 3 ) are sampled while SHPn is high level.

### 5.2 Sample and Hold Circuit

The sample and hold circuit samples and holds the video signals input to $\mathrm{C} 1 \sim \mathrm{C} 3$ selected by the multiplexer circuit in the timing shown below. Swa1 to Swb2 are reset by the RESET signal and change at the rising and falling edges of the INH signal.


### 5.3 Output Operation Timing

The sampled video signals are output to the LCD panel by output currents Ivol and Ivor via output buffer.
And be sure to input 5 or more CLKs of CLI1 during INH=H period.
The output operation of this IC is controlled by INH signals.

$$
\begin{aligned}
& \text { INH }=\mathrm{Hi}-\mathrm{Z} \\
& \text { INH }=\text { Connected with internal circuit (switch sample and hold circuit at the falling edge.) }
\end{aligned}
$$

Therefore, inverting Vсом while $\mathrm{INH}=\mathrm{L}$ causes current flow to the IC output pins, which may result wrong working. Vсом Inversion should be done during $\mathrm{INH}=\mathrm{H}(\mathrm{Hi}-\mathrm{Z})$ and output operation to the LCD should be done after the Vсом becomes stable enough.
Be sure to sufficiently evaluate the picture quality.


Cautions 1. In order to prevent destruction due to latch-up, keep the power-on sequence [ $V_{\text {DD } 1} \rightarrow$ logic input $\rightarrow$ VDD2 $\rightarrow$ video signal input ] and power-off in the reverse sequence. Observe this power sequence even during the transition period.
2. The $\mu$ PD16782A is designed to input successive signals such as chrome signals. The input band of the video signals is designed to be 9 MHz MAX. If video signals faster than that are input, display is not performed correctly.
3. Insert a bypass capacitor of $0.1 \mu \mathrm{~F}$ between $\mathrm{V}_{\mathrm{dD} 1}$ and $\mathrm{V}_{\mathrm{ss} 1}$ and between $\mathrm{V}_{\mathrm{dD} 2}$ and $\mathrm{V}_{\mathrm{ss} 2}$. If the power supply is not reinforced, the sampling voltage may be abnormal if the supply voltage fluctuates.
4. Even if the start pulse width is extended by half a clock or more, sampling start timing $\mathbf{S H P}_{1}$ is not affected, and the sampling operation is performed normally.
5. To reset the IC after power-on, the below timing sequence should be kept. (The following timing charts show simultaneous sampling.)

If RESET signal is input 1 time after power-on, it is not required after that. Besides, please be sure to input INH signal after RESET signal input.

RESET pulse width: 66 ns MIN.
tr-1: $\mathbf{8 1} \mathbf{n s}$ MIN.
INH pulse width: 5 CLK MIN. (CLI1 is active)


## 6. ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings ( $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{Vss} 1=0 \mathrm{~V}$ )

| Parameter | Symbol | Condition | Ratings | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Logic supply voltage | VDD1 |  | -0.5 to +6.0 | V |
| Driver supply voltage | VDD2 |  | -0.5 to +6.0 | V |
| Logic input voltage | $\mathrm{V}_{1}$ |  | -0.5 to $\mathrm{V}_{\text {DD } 1}+0.5$ | V |
| Video input voltage | Vvi | C1 to C3 | -0.5 to V $\mathrm{DD2} 2+0.5$ | V |
| Logic output voltage | $\mathrm{V}_{01}$ |  | -0.5 to $\mathrm{V}_{\text {DD } 1}+0.5$ | V |
| Driver output voltage | $\mathrm{V}_{02}$ |  | -0.5 to V $\mathrm{DD2} 2+0.5$ | V |
| Driver output current | lo2 |  | $\pm 10$ | mA |
| Operating ambient temperature | $\mathrm{T}_{\mathrm{A}}$ |  | -30 to +85 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature | $\mathrm{T}_{\text {stg }}$ |  | -65 to +125 | ${ }^{\circ} \mathrm{C}$ |

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

Recommended Operating Conditions ( $\mathrm{T}_{\mathrm{A}}=-\mathbf{3 0}$ to $+85^{\circ} \mathrm{C}, \mathrm{Vss} 1=\mathrm{Vss} 2=0 \mathrm{~V}$ )

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| Logic supply voltage | $\mathrm{V}_{\mathrm{DD} 1}$ |  | 3.0 | 3.3 | 5.5 | V |
| Driver supply voltage | $\mathrm{V}_{\mathrm{DD} 2}$ |  | 4.5 | 5.0 | 5.5 | V |
| Video input voltage | $\mathrm{V}_{\mathrm{VI}}$ |  | $\mathrm{V}_{\mathrm{ss} 2}+0.2$ |  | $\mathrm{~V}_{\mathrm{DD} 2}-0.2$ | V |
| Driver output voltage | $\mathrm{V}_{02}$ |  | $\mathrm{~V}_{\mathrm{SS} 2}+0.2$ |  | $\mathrm{~V}_{\mathrm{DD} 2}-0.2$ | V |
| High level Input voltage | $\mathrm{V}_{\mathrm{IH}}$ |  |  | $0.7 \mathrm{~V}_{\mathrm{DD} 1}$ |  | $\mathrm{~V}_{\mathrm{DD} 1}$ |
| Low level Input voltage | $\mathrm{V}_{\mathrm{IL}}$ | 0 |  | V |  |  |

Electrical Characteristics ( $\mathrm{T}_{\mathrm{A}}=-30$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{DD} 1}=3.0$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 2}=5.0 \mathrm{~V} \pm 0.5 \mathrm{~V}, \mathrm{Vss} 1=\mathrm{Vss}^{2}=0 \mathrm{~V}$ )

| Parameter | Symbol | Condition |  | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Maximum video signal output voltage | Vvor |  |  | VDD2 - 0.2 |  |  | V |
| Minimum video signal output voltage | VvoL |  |  |  |  | 0.2 | V |
| Logic high level output voltage | VLoh | STHL, STHR pins, $\mathrm{loh}=-1.0 \mathrm{~mA}$ |  | 0.9 VDD1 |  |  | V |
| Logic low level output voltage | V LoL | STHL, STHR pins, loL $=1.0 \mathrm{~mA}$ |  |  |  | $0.1 \mathrm{VDD1}$ | V |
| Video signal high level output current | Ivor | $\begin{aligned} & \mathrm{INH}=\mathrm{L}, \mathrm{~V}_{\mathrm{OF}}=\mathrm{V}_{\mathrm{DD} 2}-1.0 \mathrm{~V}, \\ & \mathrm{~V}_{\mathrm{O}}=\mathrm{V}_{\mathrm{DD} 2}-0.5 \mathrm{~V} \end{aligned}$ |  |  | -0.20 | -0.08 | mA |
| Video signal low level output current | IvoL | $\mathrm{INH}=\mathrm{L}, \mathrm{V}_{\text {OF }}=1.0 \mathrm{~V}, \mathrm{~V}_{0}=0.5 \mathrm{~V}$ |  | 0.08 | 0.20 |  | mA |
| Reference voltage 1 | VREF1 | $\mathrm{V}_{\mathrm{DD} 2}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{VI}}=0.5 \mathrm{~V}$ |  |  | 0.49 |  | V |
| Reference voltage 2 | VREF2 | $\mathrm{V}_{\mathrm{DD} 2}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{VI}}=2.0 \mathrm{~V}$ |  |  | 1.99 |  | V |
| Reference voltage 3 | VREF3 | $\mathrm{V}_{\mathrm{DD} 2}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{VI}}=3.5 \mathrm{~V}$ |  |  | 3.49 |  | V |
| Output voltage deviation 1 | $\Delta \mathrm{V}$ vo1 | $\mathrm{V}_{\text {DD } 2}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{VI}}=0.5 \mathrm{~V}$ |  |  |  | $\pm 30$ | mV |
| Output voltage deviation 2 | $\Delta \mathrm{V}$ Vo2 | $\mathrm{V}_{\mathrm{DD} 2}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{VVI}^{2}=2.0 \mathrm{~V}$ |  |  |  | $\pm 30$ | mV |
| Output voltage deviation 3 | $\Delta \mathrm{V}$ vo3 | $\mathrm{V}_{\mathrm{DD} 2}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{VVI}=3.5 \mathrm{~V}$ |  |  |  | $\pm 30$ | mV |
| Logic input leakage current | ILL | Logic input except Osel |  |  |  | $\pm 1.0$ | $\mu \mathrm{A}$ |
|  |  | $\mathrm{Osel}^{\text {sel }} \mathrm{V}$ I $=\mathrm{V}_{\text {DD }}=3.3 \mathrm{~V}$ |  |  | 90 |  | $\mu \mathrm{A}$ |
| Video input leakage current | IvL |  |  |  |  | $\pm 10$ | $\mu \mathrm{A}$ |
| Logic dynamic current consumption | ldD1 | $\begin{aligned} \mathrm{fcLI} & =14 \mathrm{MHz} \\ \mathrm{VvI} & =2.0 \mathrm{~V}, \end{aligned}$ <br> no load, $\begin{aligned} & \text { fiNH }=15.4 \mathrm{kHz}, \\ & \mathrm{PW} \mathrm{INH}=5.0 \mu \mathrm{~s} \end{aligned}$ | V DD $=3.3 \pm 0.3 \mathrm{~V}$ |  |  | 3 | mA |
|  |  |  | $\mathrm{V}_{\mathrm{DD} 1}=5.0 \pm 0.5 \mathrm{~V}$ |  |  | 4.5 | mA |
| Driver dynamic current consumption | IDD2 | $\begin{aligned} & \text { fCLI }=14 \mathrm{MHz} \\ & \mathrm{VVI}^{2}=2.0 \mathrm{~V}, \\ & \text { no load, } \\ & \text { fiNH }=15.4 \mathrm{kHz}, \\ & \text { PWINH }=5.0 \mu \mathrm{~s} \\ & \hline \end{aligned}$ |  |  |  | 12 | mA |

Remarks 1. Vof: output applied voltage, Vo: output voltage without load
2. The reference values are typical values only. The output deviation is only guaranteed within the chip.

Switching Characteristics ( $\mathrm{T}_{\mathrm{A}}=-30$ to $+85^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{DD} 1}=3.0$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 2}=5.0 \mathrm{~V} \pm 0.5 \mathrm{~V}, \mathrm{Vss} 1=\mathrm{V}_{\mathrm{SS} 2}=0 \mathrm{~V}$ )

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Start pulse propagation delay time | tPHL | $\mathrm{CL}_{\mathrm{L}}=20 \mathrm{pF}$ | 10 |  | 54 | ns |
|  | tPLH | $\mathrm{CL}_{\mathrm{L}}=20 \mathrm{pF}$ | 10 |  | 54 | ns |
| Clock frequency 1 | fclki |  |  |  | 15 | MHz |
| Clock frequency 2 | fclk2 | With 3-phase clock input |  |  | 15 | MHz |
| Logic input capacitance | $\mathrm{Cli}_{1}$ | Other than STHL, STHR |  |  | 15 | pF |
| STHL, STHR input capacitance | $\mathrm{Cl}_{12}$ | STHL, STHR |  |  | 20 | pF |
| Video input capacitance | $\mathrm{C}_{3}$ | C 1 to $\mathrm{C} 3, \mathrm{~V}_{\mathrm{VI}}=2.0 \mathrm{~V}$ |  |  | 50 | pF |

Timing Requirements ( $\mathrm{T}_{\mathrm{A}}=-30$ to $+85^{\circ} \mathrm{C}, \mathrm{VDD}_{\mathrm{D} 1}=3.0$ to $5.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD} 2}=5.0 \mathrm{~V} \pm 0.5 \mathrm{~V}, \mathrm{~V}_{\mathrm{ss} 1}=\mathrm{V}_{\mathrm{ss} 2}=0 \mathrm{~V}$ )

| Parameter | Symbol | Condition | MIN. | TYP. | MAX. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Clock pulse width | PWcli | Duty = 50\% | 33 |  |  | ns |
| CLK-CLK time | tcL1-2 |  | 16.6 |  |  | ns |
|  | tcL2-3 |  | 16.6 |  |  | ns |
|  | tcL3-1 |  | 16.6 |  |  | ns |
|  |  | tcL1-2 + tcL2-3 + tcL3-1 |  |  | 1/fclis | ns |
| Start pulse setup time | tsetup |  | 8 |  |  | ns |
| Start pulse hold time | thold |  | 8 |  |  | ns |
| Reset pulse width | PWres |  | 66 |  |  | ns |
| INH setup time | tisetup |  | 33 |  |  | ns |
| INH hold time | tihold |  | 33 |  |  | ns |
| Reset-INH time | $t_{\text {R-I }}$ |  | 81 |  |  | ns |
| INH pulse width | PWInh | CLI1 | 5 |  |  | CLK |

Remark Keep the rise and fall times of the logic input signals to within $\mathrm{tr}_{\mathrm{t}}=\mathrm{tf}_{\mathrm{f}}=5 \mathrm{~ns}$ ( 10 to $90 \%$ ). As an example, the switching characteristic wave of CLI1 is defined on the next page.

## Switching Characteristic Waveform (Simultaneous/successive sampling)

## Start Pulse Input Timing



Start Pulse Output Timing


Remark The input/output timing of the start pulse is the same for simultaneous/successive sampling.

## Clock Input Timing



RESET INH Pulse Timing


## NOTES FOR CMOS DEVICES

## PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:
Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.
(2) HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:
No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.
(3) STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:
Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

## Reference Documents

NEC Semiconductor Device Reliability/Quality Control System (C10983E)<br>Quality Grades On NEC Semiconductor Devices (C11531E)

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